

## ADDENDUM TO “THE CONVEX-HULL LIKE PROPERTY AND SUPPORTED IMAGES OF OPEN SETS”

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A function  $\psi : \mathbf{R}^n \rightarrow \mathbf{R}$  is said to be quasi-convex if, for each  $r \in \mathbf{R}$ , the set  $\psi^{-1}(]-\infty, r])$  is convex.

In the sequel,  $\Omega \subset \mathbf{R}^n$  is a non-empty open bounded set.

Let  $f : \Omega \rightarrow \mathbf{R}^n$  be a continuous function.

In [2], we introduced the following definition: the function  $f$  is said to satisfy the convex hull-like property if, for every continuous and quasi-convex function  $\psi : \mathbf{R}^n \rightarrow \mathbf{R}$ , there exists  $x^* \in \partial\Omega$  such that

$$\limsup_{x \rightarrow x^*} \psi(f(x)) = \sup_{x \in \Omega} \psi(f(x)) .$$

In [2], we also remarked that, given a continuous function  $g : \overline{\Omega} \rightarrow \mathbf{R}^n$ , the function  $g|_{\Omega}$  satisfies the convex hull-like property if and only if

$$g(\Omega) \subseteq \text{conv}(g(\partial\Omega)) ,$$

$\text{conv}(g(\partial\Omega))$  being the convex hull of  $g(\partial\Omega)$ .

Further, we recall that a set  $S \subseteq \mathbf{R}^n$  is said to be supported at the point  $y_0 \in S$  if there exists a non-zero linear function  $\varphi : \mathbf{R}^n \rightarrow \mathbf{R}$  such that  $\varphi(y_0) \leq \varphi(y)$  for all  $y \in S$ .

If this happens, of course  $y_0 \in \partial S$ .

The basic result of [2] is as follows:

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**Theorem 0.1** ([2], Theorem 1.5). *For any continuous function  $f : \Omega \rightarrow \mathbf{R}^n$ , at least one of the following assertions holds:*

- (i)  *$f$  satisfies the convex hull-like property in  $\Omega$ .*
- (ii) *There exists a non-empty open set  $X \subseteq \Omega$ , with  $\bar{X} \subseteq \Omega$ , satisfying the following property: for every continuous function  $g : \Omega \rightarrow \mathbf{R}^n$ , there exists  $\tilde{\lambda} \geq 0$  such that, for each  $\lambda > \tilde{\lambda}$ , the set  $(g + \lambda f)(X)$  is supported at one of its points.*

Next, if  $A \subseteq \mathbf{R}^n$  is a non-empty open set,  $x \in A$  and  $\varphi : A \rightarrow \mathbf{R}^n$  is a  $C^1$  function, we denote by  $\det(J_\varphi(x))$  the Jacobian determinant of  $\varphi$  at  $x$ .

Always in [2], as a joint application of Theorem 0.1 and the classical local inverse function theorem, we obtained the following result:

**Theorem 0.2** ([2], Theorem 3.3). *Let  $f : \Omega \rightarrow \mathbf{R}^n$  be a  $C^1$  function. Then, at least one of the following assertions holds:*

- (a<sub>1</sub>)  *$f$  satisfies the convex hull-like property in  $\Omega$ .*
- (a<sub>2</sub>) *There exists a non-empty open set  $X \subseteq \Omega$ , with  $\bar{X} \subseteq \Omega$ , satisfying the following property: for every continuous function  $g : \Omega \rightarrow \mathbf{R}^n$  which is  $C^1$  in  $X$ , there exists  $\tilde{\lambda} \geq 0$  such that, for each  $\lambda > \tilde{\lambda}$ , the set*

$$\{x \in X : \det(J_{g+\lambda f}(x)) = 0\}$$

*is non-empty.*

The aim of the present addendum is to remark that, using Theorem 0.1 jointly with a very recent result by J. Saint Raymond [3], Theorem 0.2 can be improved in a very remarkable way. Actually, Saint Raymond proved the following very interesting result (for anything concerning topological dimension, we refer to [1]):

**Theorem 0.3** ([3], Theorem 3.4). *Let  $A \subseteq \mathbf{R}^n$  be a non-empty open set and  $\varphi : A \rightarrow \mathbf{R}^n$  a  $C^1$  function such that the topological dimension of the set*

$$\{x \in A : \det(J_\varphi(x)) = 0\}$$

*is not positive. Then, the function  $\varphi$  is open.*

Finally, the improvement of Theorem 0.2, object of this addendum, is as follows:

**Theorem 0.4.** *Let  $f : \Omega \rightarrow \mathbf{R}^n$  be a  $C^1$  function. Then, at least one of the following assertions holds:*

- (a<sub>1</sub>) *f* satisfies the convex hull-like property in  $\Omega$ .
- (a<sub>2</sub>) *There exists a non-empty open set  $X \subseteq \Omega$ , with  $\overline{X} \subseteq \Omega$ , satisfying the following property: for every continuous function  $g : \Omega \rightarrow \mathbf{R}^n$  which is  $C^1$  in  $X$ , there exists  $\tilde{\lambda} \geq 0$  such that, for each  $\lambda > \tilde{\lambda}$ , the topological dimension of the set*

$$\{x \in X : \det(J_{g+\lambda f}(x)) = 0\}$$

*is greater than or equal 1.*

*Proof.* Assume that (a<sub>1</sub>) does not hold. Let  $X$  be an open set as in point (ii) of Theorem 0.1. Let  $g : \Omega \rightarrow \mathbf{R}^n$  be a continuous function which is  $C^1$  in  $X$ . Then, there is some  $\tilde{\lambda} \geq 0$  such that, for each  $\lambda > \tilde{\lambda}$ , there exists  $\hat{x} \in X$  such that the set  $(g + \lambda f)(X)$  is supported at  $g(\hat{x}) + \lambda f(\hat{x})$ . As already remarked, this implies that  $g(\hat{x}) + \lambda f(\hat{x}) \in \partial(g + \lambda f)(X)$  and so  $(g + \lambda f)(X)$  is not open. Now, (a<sub>2</sub>) is a direct consequence of Theorem 0.3.  $\square$

## REFERENCES

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