

SOME REMARKS ON A RECENT CRITICAL POINT RESULT OF NONSMOOTH ANALYSIS

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The aim of this paper is to investigate some consequences of a nonsmooth version, established in [13], of Ghoussoub's general min-max principle [8, Theorem 1]. An application to a class of elliptic variational-hemivariational inequalities is also pointed out.

1. Introduction

In a recent paper [13], a general min-max principle for C^1 -functions obtained by Ghoussoub [8, Theorem 1] has been extended to functionals f , on an infinite dimensional Banach space X , fulfilling the structural hypothesis

(H'_f) $f(x) := \Phi(x) + \psi(x)$ for all $x \in X$, where $\Phi : X \rightarrow \mathbb{R}$ is locally Lipschitz continuous, while $\psi : X \rightarrow \mathbb{R} \cup \{+\infty\}$ turns out convex, proper, and lower semicontinuous. Moreover, ψ is continuous on any nonempty compact set $A \subseteq X$ such that $\sup_{x \in A} \psi(x) < +\infty$.

Likewise the C^1 -setting, this result leads to a nonsmooth version [12, Theorem 3.1] of the famous critical point theorem in presence of splitting established by Brézis and Nirenberg [2, Theorem 4].

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The main purpose of this paper is to present some consequences of both Theorem 3.1 in [13] and Theorem 3.1 of [12]. Section 2 is devoted to basic definitions and preliminary results. In Section 3 we first point out an immediate but useful consequence of Theorem 3.1 in [13]; see Theorem 3.2 below. In the locally Lipschitz continuous case, this result has already been obtained by X. Wu [15] through a different and longer proof. The above-mentioned nonsmooth version of Brézis-Nirenberg's critical point theorem is then presented and discussed; vide Theorem 3.3 below. Finally, Section 4 contains an application of Theorem 3.3 to an elliptic variational-hemivariational inequality problem. More precisely, let Ω be a nonempty, bounded, open subset of the real Euclidean N -space $(\mathbb{R}^N, |\cdot|)$, $N \geq 3$, having a smooth boundary $\partial\Omega$, and let

$$\mathcal{G}(u) := \int_{\Omega} G(x, u(x)) dx, \quad u \in H_0^1(\Omega),$$

where $G(x, \xi) := \int_0^{\xi} -g(x, t) dt$ for all $(x, \xi) \in \Omega \times \mathbb{R}$, and

(h₁) $g : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a locally bounded measurable function such that

$$-\infty < \liminf_{|t| \rightarrow \infty} \frac{g(x, t)}{t} \leq \limsup_{|t| \rightarrow \infty} \frac{g(x, t)}{t} < \lambda_1,$$

uniformly in $x \in \Omega$.

Here, as usual, λ_1 denotes the first eigenvalue of $-\Delta$ in $H_0^1(\Omega)$. The function \mathcal{G} is well defined and locally Lipschitz continuous. Hence, we can consider its generalized directional derivative \mathcal{G}^0 in the sense of Clarke [4].

Let K be a suitable nonempty, convex, closed subset of $H_0^1(\Omega)$ and let (P_K) denote the following elliptic variational-hemivariational inequality problem:

Find $u \in K$ such that

$$-\int_{\Omega} \nabla u(x) \cdot \nabla(v - u)(x) dx \leq \mathcal{G}^0(u; v - u)$$

for all $v \in K$.

We shall prove that if g satisfies appropriate growth conditions, then (P_K) possesses at least two nontrivial solutions; see Theorem 4.1. Moreover, when

$$g^-(x, t) := \lim_{\delta \rightarrow 0} \inf_{|\xi - t| < \delta} g(x, \xi), \quad g^+(x, t) := \lim_{\delta \rightarrow 0} \sup_{|\xi - t| < \delta} g(x, \xi),$$

turn out to be superposition measurable and $K := H_0^1(\Omega)$ one actually has two nontrivial solutions of the following multivalued Dirichlet problem:

Find $u \in H_0^1(\Omega)$ such that

$$\begin{cases} -\Delta u \in [g^-(x, u), g^+(x, u)] & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (\text{W})$$

Let us finally note that Problem (W) has previously been investigated in [15] under different assumptions on the datum g ; vide Remark 4.4.

2. Basic definitions and auxiliary results

Let $(X, \|\cdot\|)$ be a real Banach space. If V is a subset of X , we write \bar{V} for the closure of V and ∂V for its boundary. When V is nonempty, $x \in X$, and $\delta > 0$, we define $B(x, \delta) := \{z \in X : \|z - x\| < \delta\}$ and

$$d(x, V) := \inf_{z \in V} \|x - z\|.$$

Given $x, z \in X$, the symbol $[x, z]$ indicates the line segment joining x to z , namely

$$[x, z] := \{(1 - t)x + tz : t \in [0, 1]\}.$$

We denote by X^* the dual space of X , while $\langle \cdot, \cdot \rangle$ stands for the duality pairing between X^* and X . A function $\Phi : X \rightarrow \mathbb{R}$ is called locally Lipschitz continuous when to every $x \in X$ there correspond a neighbourhood V_x of x and a constant $L_x \geq 0$ such that

$$|\Phi(z) - \Phi(w)| \leq L_x \|z - w\| \quad \forall z, w \in V_x.$$

If $x, z \in X$, we write $\Phi^0(x; z)$ for the generalized directional derivative of Φ at the point x along the direction z , i.e.,

$$\Phi^0(x; z) := \limsup_{w \rightarrow x, t \rightarrow 0^+} \Phi(w + tz) - \frac{\Phi(w)}{t}.$$

It is known [4, Proposition 2.1.1] that Φ^0 is upper semicontinuous on $X \times X$. The generalized gradient of the function Φ in x , denoted by $\partial\Phi(x)$, is the set

$$\partial\Phi(x) := \{x^* \in X^* : \langle x^*, z \rangle \leq \Phi^0(x; z) \forall z \in X\}.$$

Proposition 2.1.2 of [4] ensures that $\partial\Phi(x)$ turns out nonempty, convex, in addition to weak* compact.

Let f be a function on X satisfying the structural hypothesis (H'_f) . Put $D_\psi := \{x \in X : \psi(x) < +\infty\}$. Since ψ is continuous on $\text{int}(D_\psi)$ (see for instance [5,

Exercise 1, p. 296]), the same holds regarding f . We say that $x \in D_\psi$ is a critical point of f when

$$\Phi^0(x; z - x) + \psi(z) - \psi(x) \geq 0 \quad \forall z \in X.$$

If $\psi \equiv 0$, it clearly signifies $0 \in \partial\Phi(x)$, namely x is a critical point of Φ according to [3, Definition 2.1].

Let S be a nonempty closed subset of X . The function f is said to fulfil the Palais-Smale condition at the level c and around the set S provided

(PS) $_{S,c}$ Every sequence $\{x_n\} \subseteq X$ such that $d(x_n, S) \rightarrow 0$, $f(x_n) \rightarrow c$, and

$$\Phi^0(x_n; x - x_n) + \psi(x) - \psi(x_n) \geq -\varepsilon_n \|x - x_n\| \quad (1)$$

for all $n \in \mathbb{N}$ and $x \in X$, where $\varepsilon_n \rightarrow 0^+$, possesses a convergent subsequence.

When $S = X$ we simply write (PS) $_c$ in place of (PS) $_{S,c}$. Moreover f satisfies (PS) $_f$ means that (PS) $_c$ hold true at any level c .

3. Some remarks on a recent critical point theorem

Let B be a nonempty closed subset of X and let \mathcal{F} be a class of nonempty compact sets in X . We say that \mathcal{F} is a homotopy-stable family with extended boundary B when for every $A \in \mathcal{F}$ and every $\eta \in C^0([0, 1] \times X, X)$ such that $\eta(t, x) = x$ in $(\{0\} \times X) \cup ([0, 1] \times B)$ one has $\eta(\{1\} \times A) \in \mathcal{F}$. The following assumptions will be posited in the sequel.

(a₁) \mathcal{F} is a homotopy-stable family with extended boundary B , the function f fulfills condition (H' $_f$), and

$$c = \inf_{A \in \mathcal{F}} \sup_{x \in A} f(x) < +\infty.$$

(a₂) There exists a closed subset F of X such that

$$(A \cap F) \setminus B \neq \emptyset \quad \forall A \in \mathcal{F}, \quad (2)$$

and, moreover,

$$\sup_{x \in B} f(x) \leq \inf_{x \in F} f(x). \quad (3)$$

Gathering (a₁) and (a₂) together one has

$$\inf_{x \in F} f(x) \leq c. \quad (4)$$

The next result [13, Theorem 3.1] holds.

Theorem 3.1. *Let (a_1) and (a_2) be satisfied. Then to every sequence $\{A_n\} \subseteq \mathcal{F}$ such that $\lim_{n \rightarrow +\infty} \sup_{x \in A_n} f(x) = c$ there corresponds a sequence $\{x_n\} \subseteq X \setminus B$ having the following properties:*

$$(i_1) \quad \lim_{n \rightarrow +\infty} f(x_n) = c.$$

$$(i_2) \quad \Phi^0(x_n; z - x_n) + \Psi(z) - \Psi(x_n) \geq -\varepsilon_n \|z - x_n\|, \forall n \in \mathbb{N}, z \in X, \text{ where } \varepsilon_n \rightarrow 0^+.$$

$$(i_3) \quad \lim_{n \rightarrow +\infty} d(x_n, F) = 0 \text{ provided } \inf_{x \in F} f(x) = c.$$

$$(i_4) \quad \lim_{n \rightarrow +\infty} d(x_n, A_n) = 0.$$

Now, let X be reflexive, let K be a compact metric space, and let K^* be a nonempty closed subset of K . Define $\mathcal{A} = \{p \in C^0(K, X) : p|_{K^*} = p^*\}$, where $p^* : K^* \rightarrow X$ is a fixed continuous function. If

$$c := \inf_{p \in \mathcal{A}} \sup_{x \in K} f(p(x)),$$

then $c \geq \sup_{x \in K^*} f(p^*(x))$.

An immediate consequence of Theorem 3.1 is the following.

Theorem 3.2. *Let the function $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$ fulfill the following assumptions in addition to (H_f') .*

$$(j_1) \quad \sup_{x \in K} f(p(x)) < +\infty \text{ for some } p \in \mathcal{A}.$$

$$(j_2) \quad \text{There exists a closed subset } D \text{ of } X \text{ such that } (p(K) \cap D) \setminus p^*(K^*) \neq \emptyset \text{ for every } p \in \mathcal{A} \text{ and, moreover, } \sup_{x \in K^*} f(p^*(x)) \leq \inf_{x \in D} f(x).$$

Then there is a sequence $\{u_n\} \subseteq X$ having properties (i_1) – (i_3) , with $F := D$. If, in addition, f satisfies condition $(PS)_c$, then it has a critical point $u \in D$ such that $f(u) = c$.

Proof. Define $B := p^*(K^*)$. Obviously, setting

$$\mathcal{F} := \{p(K) : p \in \mathcal{A}\}$$

we obtain a homotopy-stable family with extended boundary B . Moreover, thanks (j_1) , $c = \inf_{p \in \mathcal{A}} \sup_{x \in K} f(p(x)) < +\infty$. Hence, (a_1) holds true. Bearing in mind (j_2) yields (a_2) . Now, the conclusion is an immediate consequence of Theorem 3.1. \square

Remark 3.3. In the locally Lipschitz continuous case, Theorem 3.2 has been established by X. Wu in [15] using different methods and a longer proof. We also point out that weaker Palais-Smale's type compactness conditions might be adopted once one exploits Theorem 3.1 of [11].

Now, let X be reflexive and let f be a function from X into $\mathbb{R} \cup \{+\infty\}$. The following hypothesis will be posited in the sequel:

(f₁) f is bounded below and fulfils $(PS)_f$ besides (H'_f) ,

(f₂) x_0 is a global minimum point of the function f .

Since under (f₁) each minimizing sequence for f possesses a convergent subsequence (see [12]), the function f must attain its minimum at some point $x_0 \in X$. So, (f₂) is quite natural. Suppose further

$$X := X_1 \oplus X_2,$$

where $\dim(X_1) > 0$, while $0 < \dim(X_2) < \infty$.

The following nonsmooth version of the famous Brézis-Nirenberg critical point theorem in presence of splitting is proved in [12].

Theorem 3.4. *If (f₁)–(f₂) are satisfied, $\inf_{x \in X} f(x) < f(0)$, $f(0) = 0$, and, moreover,*

(f₃) *the set $\{x \in X : f(x) < a\}$ is open for some constant $a > 0$,*

(f₄) *there exists an $r \in]0, \frac{\|x_0\|}{2}[$ such that $f|_{\overline{B}(0,r) \cap X_1} \geq 0$, $f|_{\overline{B}(0,r) \cap X_2} \leq 0$, and $f|_{\partial B(0,r) \cap X_2} < 0$,*

then the function f possesses at least two nontrivial critical points.

Remark 3.5. Hypothesis (f₄) is obviously fulfilled in the meaningful special case when

(f'₄) *for some $r > 0$ one has $f|_{\overline{B}(0,r) \cap X_1} \geq 0$ as well as $f|_{\overline{B}(0,r) \cap X_2 \setminus \{0\}} < 0$,*

namely 0 turns out a local minimum of $f|_{X_1}$ and a proper local maximum for $f|_{X_2}$.

Assuming that f is a locally Lipschitz continuous, i.e. $\psi \equiv 0$, and substituting hypothesis (f₄) with

(f^{*}₄) *there exists a positive constant r such that $f|_{\overline{B}(0,r) \cap X_1} \geq 0$, $f|_{\overline{B}(0,r) \cap X_2} \leq 0$,*

one can get Theorem 2.3 of [15].

4. Application

Let Ω and $g : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be as in the Introduction. The main purpose of this section is to investigate a variational-hemivariational inequality version of Problem (W). The symbol $H_0^1(\Omega)$ indicates the closure of $C_0^\infty(\Omega)$ in $W^{1,2}(\Omega)$ with respect to the norm

$$\|u\| := \left(\int_{\Omega} |\nabla u(x)|^2 dx \right)^{\frac{1}{2}}.$$

Denote by 2^* the critical exponent for the Sobolev embedding $H_0^1(\Omega) \hookrightarrow L^p(\Omega)$. Recall that $2^* = \frac{2N}{N-2}$, if $p \in [1, 2^*]$ then there exists a positive constant c_p such that

$$\|u\|_{L^p(\Omega)} \leq c_p \|u\|, \quad u \in H_0^1(\Omega), \tag{5}$$

and, in particular, the embedding is compact whenever $p \in [1, 2^*[$; see e.g.[14, Proposition B.7].

Consider the following eigenvalue problem

$$\begin{cases} -\Delta u = \lambda u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{6}$$

It is well known [7, Section 8.12] that (6) possesses a sequence $\{\lambda_n\}$ of eigenvalues fulfilling $0 < \lambda_1 < \lambda_2 \leq \dots \leq \lambda_n \leq \dots$. The number of times an eigenvalue appears in the sequence equals its multiplicity.

Let $\{\varphi_n\}$ be a corresponding sequence of eigenfunctions normalized as follows:

$$\int_{\Omega} |\nabla \varphi_n(x)|^2 dx = \lambda_n \int_{\Omega} \varphi_n(x)^2 dx = \lambda_n \quad \forall n \in \mathbb{N}; \tag{7}$$

$$\int_{\Omega} \nabla \varphi_m(x) \cdot \nabla \varphi_n(x) dx = \int_{\Omega} \varphi_m(x) \varphi_n(x) dx = 0, \tag{8}$$

provided $m, n \in \mathbb{N}$ and $m \neq n$.

By (h₁) there are constants $\varepsilon \in]0, \lambda_1[$ and $r > 0$ such that

$$g(x, t) < (\lambda_1 - \varepsilon)t \tag{9}$$

for all $|t| \geq r$ and $x \in \Omega$. Since g is locally bounded, we also have

$$M := \sup_{(x,t) \in \Omega \times [-r,r]} |g(x, t)| < +\infty. \tag{10}$$

Now, let $\kappa > 0$. Define

$$r_\kappa := \sqrt{\frac{\kappa + Mr\mu(\Omega)}{\varepsilon}} 2\lambda_1, \tag{11}$$

where $\mu(\Omega)$ is the Lebesgue measure of Ω . A set $K \subseteq H_0^1(\Omega)$ is called of type (K) provided

(K) K turns out to be nonempty, convex, closed in $H_0^1(\Omega)$. Moreover, there exists a $\kappa > 0$ such that $\bar{B}(0, r_\kappa) \subset K$.

The following result provides an application of Theorem 3.3.

Theorem 4.1. *Let g satisfy condition (h_1) and let K be of type (K) . Assume that there exists an integer $k \geq 1$ such that*

$$\lambda_k < \lambda_{k+1}. \tag{12}$$

If, moreover,

$$\liminf_{\xi \rightarrow 0} \frac{\int_0^\xi g(x, t) dt}{|\xi|^2} > \frac{\lambda_k}{2}, \tag{13}$$

and

$$\limsup_{|\xi| \rightarrow 0} \frac{g(x, \xi)}{\xi} < \lambda_{k+1} \tag{14}$$

uniformly in $x \in \Omega$, then Problem (P_K) possesses at least two nontrivial solutions.

Proof. Pick $X := H_0^1(\Omega)$, $p \in]2, 2^*[$ and define, whenever $u \in X$,

$$\Phi(u) := \frac{1}{2} \int_\Omega |\nabla u(x)|^2 dx + \mathcal{G}(u),$$

as well as

$$\psi(u) := \begin{cases} 0 & \text{if } u \in K, \\ +\infty & \text{otherwise,} \end{cases} \quad f(u) := \Phi(u) + \psi(u).$$

Owing to (h_1) the function $\Phi : X \rightarrow \mathbb{R}$ turns out to be locally Lipschitz continuous. Consequently, f satisfies condition (H'_f) .

We shall prove that f is bounded from below and coercive. By (9) and (10) one has

$$\int_0^\xi g(x, t) dt \leq Mr + \frac{1}{2}(\lambda_1 - \varepsilon)\xi^2 \quad \forall \xi \in \mathbb{R}. \tag{15}$$

Hence,

$$\begin{aligned} f(u) &\geq \Phi(u) = \\ &= \frac{1}{2}\|u\|^2 - \int_{\Omega} dx \int_0^{u(x)} g(x,t) dt \\ &\geq \frac{1}{2}\|u\|^2 - \int_{\Omega} \left[Mr + \frac{1}{2}(\lambda_1 - \varepsilon)|u(x)|^2 \right] dx = \\ &= \frac{1}{2}\|u\|^2 - \frac{1}{2}(\lambda_1 - \varepsilon) \int_{\Omega} |u(x)|^2 dx - Mr\mu(\Omega). \end{aligned}$$

From $\|u\|_{L^2(\Omega)} \leq \frac{1}{\sqrt{\lambda_1}}\|u\|$ (see for instance [7, p. 213]) it follows that

$$f(u) \geq \frac{1}{2}\|u\|^2 - \frac{1}{2}\left(1 - \frac{\varepsilon}{\lambda_1}\right)\|u\|^2 - Mr\mu(\Omega).$$

Thus,

$$f(u) \geq \frac{\varepsilon}{2\lambda_1}\|u\|^2 - Mr\mu(\Omega) \quad \forall u \in X, \quad (16)$$

which shows the claim.

Let us next show that the function f satisfies condition $(PS)_f$. So, pick a sequence $\{u_n\} \subseteq X$ such that $\{f(u_n)\}$ is bounded and

$$\Phi^0(u_n; v - u_n) + \Psi(v) - \Psi(u_n) \geq -\varepsilon_n \|v - u_n\| \quad (17)$$

for all $n \in \mathbb{N}$, $v \in X$, where $\varepsilon_n \rightarrow 0^+$. One evidently has $\{u_n\} \subseteq K$. Since f is coercive, the sequence $\{u_n\}$ turns out bounded. Thus, passing to a subsequence if necessary, we may suppose both $u_n \rightharpoonup u$ in X and $u_n \rightarrow u$ in $L^2(\Omega)$. The point u belongs to K because this set is weakly closed. Exploiting (17) with $v := u$ we then get

$$\int_{\Omega} \nabla u_n(x) \cdot \nabla (u - u_n)(x) dx + \mathcal{G}^0(u_n; u - u_n) \geq -\varepsilon_n \|u - u_n\| \quad \forall n \in \mathbb{N}. \quad (18)$$

The upper semicontinuity of \mathcal{G}^0 on $L^2(\Omega) \times L^2(\Omega)$ forces

$$\limsup_{n \rightarrow +\infty} \mathcal{G}^0(u_n; u - u_n) \leq \mathcal{G}^0(u; 0) = 0. \quad (19)$$

By (19), besides the weak convergence of $\{u_n\}$ to u , inequality (18) yields, as $n \rightarrow +\infty$,

$$\limsup_{n \rightarrow \infty} \int_{\Omega} |\nabla u_n(x)|^2 dx \leq \int_{\Omega} |\nabla u(x)|^2 dx.$$

Hence, thanks to [1, Proposition III.30], $u_n \rightarrow u$ in X , i.e., hypothesis (f_1) of Theorem 3.3 is fulfilled.

The next step is to verify (f_3) . Since K is of type (K) , there exists a $\kappa > 0$ such that the set $\{u \in X : f(u) < \kappa\}$ is open. Indeed, through (16) we obtain

$$\{u \in X : f(u) < \kappa\} \subseteq B(0, r_\kappa) \subseteq K.$$

Consequently,

$$\{u \in X : f(u) < \kappa\} = \{u \in K : \Phi(u) < \kappa\} = \{u \in X : \Phi(u) < \kappa\},$$

which is open.

Let $X_2 := \text{span}\{\varphi_1, \dots, \varphi_k\}$ and let $X_1 := X_2^\perp$, where the orthogonal complement is taken in $H_0^1(\Omega)$. One clearly has $X = X_1 \oplus X_2$, $\dim(X_1) > 0$, and $0 < \dim(X_2) < +\infty$. Due to (13) there exists a $\delta > 0$ such that

$$\int_0^\xi g(x, t) dt > \frac{\lambda_k}{2} |\xi|^2,$$

provided $0 < |\xi| < \delta$. Since X_2 is finite dimensional, we can find a positive constant $\rho_1 < r_\kappa$ such that if $u \in X_2$ and $\|u\| \leq \rho_1$, then $\|u\|_{L^\infty(\Omega)} < \delta$. So, $0 < \|u\|_{L^\infty(\Omega)} < \delta$ for all $u \in \bar{B}(0, \rho_1) \cap X_2 \setminus \{0\}$, which forces $0 \leq |u(x)| < \delta$ almost everywhere in Ω as well as $0 < |u(x)|$ in $\Omega_0 \subseteq \Omega$ with $\mu(\Omega_0) > 0$. Consequently,

$$\int_0^{u(x)} g(x, t) dt \geq \frac{\lambda_k}{2} |u(x)|^2$$

for almost all $x \in \Omega$ and with a strict inequality in Ω_0 . Now if $u \in X_2$, $u = \sum_{i=1}^k \alpha_i \varphi_i$, for suitable $\alpha_i \in \mathbb{R}$, $i = 1, \dots, k$. Owing (7) and (8) one has

$$\|u\|^2 = \sum_{i=1}^k \alpha_i^2 \int_\Omega |\nabla \varphi_i(x)|^2 dx = \sum_{i=1}^k \alpha_i^2 \lambda_i \int_\Omega \varphi_i(x)^2 dx \leq \lambda_k \int_\Omega |u(x)|^2 dx.$$

This implies

$$\begin{aligned} f(u) &= \frac{1}{2} \|u\|^2 + \int_\Omega G(x, u(x)) dx \\ &\leq \frac{\lambda_k}{2} \int_\Omega |u(x)|^2 dx - \int_\Omega \left[\int_0^{u(x)} g(x, t) dt \right] dx \\ &= \int_\Omega \left[\frac{\lambda_k}{2} |u(x)|^2 - \int_0^{u(x)} g(x, t) dt \right] dx < 0, \end{aligned}$$

which clearly means

$$f(u) < 0 \quad \forall u \in \bar{B}(0, \rho_1) \cap X_2 \setminus \{0\}. \tag{20}$$

By (14) there exist $\lambda \in]0, \lambda_{k+1}[$ and $\sigma \in]0, r[$ such that $\frac{g(x,t)}{t} < \lambda$ for every $|t| \in]0, \sigma[$ and $x \in \Omega$. Hence

$$\int_{|u(x)| < \sigma} \left[\int_0^{u(x)} g(x,t) dt \right] dx \leq \frac{\lambda}{2} \int_{\Omega} |u(x)|^2 dx. \tag{21}$$

Due to (15), one has

$$G(x, \xi) \geq -Mr - \frac{1}{2}(\lambda_1 - \varepsilon)\xi^2 \geq -\left(\frac{Mr}{\sigma^p} + \frac{\lambda_1 - \varepsilon}{\sigma^{p-2}}\right)|\xi|^p, \tag{22}$$

provided $|\xi| \geq \sigma$. The Sobolev embedding theorem gives

$$\int_{|u(x)| \geq \sigma} G(x, u(x)) dx \geq -\left(\frac{Mr}{\sigma^p} + \frac{\lambda_1 - \varepsilon}{\sigma^{p-2}}\right)\|u\|_{L^p(\Omega)} \geq -c^*\|u\|^p, \tag{23}$$

where $c^* := \left(\frac{Mr}{\sigma^p} + \frac{\lambda_1 - \varepsilon}{\sigma^{p-2}}\right)c_p^p$. Now if $u \in X_1$, $u = \sum_{j=k+1}^{+\infty} \beta_j \varphi_j$, for suitable $\beta_j \in \mathbb{R}$, $j = k+1, \dots$. Owing (7) and (8), one has

$$\|u\|_{L^2(\Omega)}^2 = \sum_{j=k+1}^{+\infty} \beta_j^2 \int_{\Omega} \varphi_j(x)^2 dx = \sum_{j=k+1}^{+\infty} \frac{\beta_j^2}{\lambda_j} \int_{\Omega} |\nabla \varphi_j(x)|^2 dx \leq \frac{1}{\lambda_{k+1}} \|u\|^2,$$

i.e.,

$$\|u\|_{L^2(\Omega)} \leq \frac{1}{\sqrt{\lambda_{k+1}}} \|u\| \tag{24}$$

for each $u \in X_1$. Then, by (21), (23) and (24) we get

$$\begin{aligned} f(u) &= \frac{1}{2}\|u\|^2 + \int_{\Omega} G(x, u(x)) dx = \\ &= \frac{1}{2}\|u\|^2 - \int_{|u(x)| < \sigma} \left[\int_0^{u(x)} g(x,t) dt \right] dx + \int_{|u(x)| \geq \sigma} G(x, u(x)) dx \geq \\ &\geq \frac{1}{2} \left(1 - \frac{\lambda}{\lambda_{k+1}}\right) \|u\|^2 - c^* \|u\|^p. \end{aligned} \tag{25}$$

Since $p > 2$, putting $\rho_2 := \left[\frac{1}{2c^*} \left(1 - \frac{\lambda}{\lambda_{k+1}}\right) \right]^{1/(p-2)}$, from (25) it follows that

$$f(u) \geq 0 \quad \forall u \in \overline{B}(0, \rho_2) \cap X_1. \tag{26}$$

Choose $\rho := \min\{\rho_1, \rho_2\}$. Then

$$f(u) < 0 \quad \forall u \in \overline{B}(0, \rho) \cap X_2,$$

and

$$f(u) \geq 0 \quad \forall u \in \overline{B}(0, \rho) \cap X_1.$$

Bearing in mind Remark 3.5, this immediately yields (f₄).

Finally, observe that by (20) one has $\inf_{u \in X} f(u) < 0$. We are in a position now to apply Theorem 3.3. Thus there exist at least two points $u_1, u_2 \in X \setminus \{0\}$ such that

$$\Phi^0(u_i; v - u_i) + \psi(v) - \psi(u_i) \geq 0$$

for all $v \in X, i = 1, 2$. The choice of ψ gives both $u_i \in K$ and $\Phi^0(u_i; v - u_i) \geq 0, v \in K, i = 1, 2$, namely u_1, u_2 turn out to be nontrivial solutions of Problem (P_K), which completes the proof. \square

Example 4.2. The aim of this example is to exhibit a non-trivial case of set in $H_0^1(\Omega)$ of type (K). Let $h : H_0^1(\Omega) \rightarrow \mathbb{R}$ be a weakly continuous and convex function. For $\bar{\kappa} > 0$ fixed, put

$$r_{\bar{\kappa}} := \sqrt{\frac{\bar{\kappa} + Mr\mu(\Omega)}{\varepsilon}} 2\lambda_1, \tag{27}$$

with the same notation as before. The ball $\overline{B}(0, r_{\bar{\kappa}})$ is a weakly compact subset of $H_0^1(\Omega)$, hence $h|_{\overline{B}(0, r_{\bar{\kappa}})}$ admits a global maximum. Then the set

$$K := \{u \in H_0^1(\Omega) : h(u) \leq \alpha + 1\},$$

where $\alpha := \max_{u \in \overline{B}(0, r_{\bar{\kappa}})} h(u)$, is a subset of $H_0^1(\Omega)$ of type (K).

Remark 4.3. Recall that a function $q : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is called superposition measurable when $x \mapsto q(x, u(x))$ is measurable for all measurable $u : \Omega \rightarrow \mathbb{R}$. Let $K := H_0^1(\Omega)$. Assume that:

(h₂) *The functions*

$$g^-(x, t) := \lim_{\delta \rightarrow 0} \inf_{|\xi - t| < \delta} g(x, \xi), \quad g^+(x, t) := \lim_{\delta \rightarrow 0} \sup_{|\xi - t| < \delta} g(x, \xi)$$

are superposition measurable.

If $u \in H_0^1(\Omega)$ complies with

$$-\int_{\Omega} \nabla u(x) \cdot \nabla(v - u)(x) dx \leq \mathcal{G}^0(u; v - u) \quad \forall v \in H_0^1(\Omega),$$

then

$$\int_{\Omega} -\Delta u(x) \cdot w(x) dx \leq (-\mathcal{G})^0(u; w), \quad w \in H_0^1(\Omega).$$

This implies

$$-\Delta u \in \partial(-\mathcal{G})(u) \subseteq \{w \in L^2(\Omega) : g^-(x, u(x)) \leq w(x) \leq g^+(x, u(x)) \text{ a.e. in } \Omega\},$$

i.e.,

$$-\Delta u(x) \in [g^-(x, u(x)), g^+(x, u(x))] \quad \text{for almost all } x \in \Omega.$$

Hence, Theorem 4.1 gives at least two nontrivial solutions of Problem (W).

Remark 4.4. Very recently, in [15], an existence result has been obtained by using hypotheses $(h_1), (h_2), (14)$, and the following one:

There exists a $\delta > 0$ such that

$$\lambda_k \leq \frac{g(x, t)}{t}$$

for all $0 < |t| < \delta$ and almost all $x \in \Omega$; cf. [15, Theorem 3.1]. It is simple matter to see that this result and Theorem 4.1 above are mutually independent.

Remark 4.5. Let Ω and $g : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be as in the Introduction and let A be a uniformly elliptic operator of the form

$$Au = - \sum_{i,j=1}^N \frac{\partial}{\partial x_j} \left(a^{ij}(x) \frac{\partial u}{\partial x_i} \right) + c(x)u,$$

where $a^{ij} : \Omega \rightarrow \mathbb{R}, i, j = 1, \dots, N$, satisfy the following conditions:

A₁) $a^{ij} = a^{ji} \in L^\infty(\Omega)$;

A₂) $c \in L^\infty(\Omega)$ and $c \geq 0$ almost everywhere in Ω ;

A₃) There is a $\gamma > 0$ such that

$$\sum_{i,j=1}^N a^{ij}(x) \xi_i \xi_j \geq \gamma |\xi|^2 \quad \forall x \in \Omega, \xi \in \mathbb{R}^N.$$

On $H_0^1(\Omega)$ we consider the norm (equivalent to the usual one)

$$\|u\| := \langle Au, u \rangle^{1/2}$$

induced by the inner product

$$\langle Au, v \rangle = \int_{\Omega} \left[\sum_{i,j=1}^N a^{ij}(x) \frac{\partial u(x)}{\partial x_i} \frac{\partial v(x)}{\partial x_j} + c(x)u(x)v(x) \right] dx,$$

see for instance [6, p. 650]. It is well known (vide Proposition 6.1.15, p. 652, and Theorem 6.1.21, p. 654, of [6]) that the eigenvalue Dirichlet problem

$$\begin{cases} Au = \lambda u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (28)$$

possesses a sequence $\{\lambda_n\}$ of eigenvalues fulfilling

$$0 < \lambda_1 < \lambda_2 \leq \dots \leq \lambda_n \leq \dots$$

and a corresponding sequence $\{\varphi_n\}$ of eigenfunctions normalized as follows:

$$\langle A\varphi_n, \varphi_n \rangle = \lambda_n \int_{\Omega} \varphi_n(x)^2 dx = \lambda_n \quad \forall n \in \mathbb{N}; \quad (29)$$

$$\langle A\varphi_n, \varphi_m \rangle = \int_{\Omega} \varphi_m(x) \varphi_n(x) dx = 0, \quad (30)$$

provided $m, n \in \mathbb{N}$ and $m \neq n$; see [6, Proposition 6.1.19, p. 653].

Arguing as in the proof of Theorem 4.1, but with Au in place of $-\Delta u$, $u \in H_0^1(\Omega)$, it is possible to obtain two nontrivial solutions of the following variational-hemivariational inequality problem:

$$\begin{cases} u \in K, \\ \langle Au, v - u \rangle + \mathcal{G}^0(u; v - u) \geq 0 \quad \forall v \in K, \end{cases} \quad (\mathbf{P}_{A,K})$$

where K is of type (K) in $H_0^1(\Omega)$. Recently, in [16], X. Wu and T. Leng studied the existence of two nontrivial solutions in $H_0^1(\Omega)$ to the problem

$$\begin{cases} Au = g(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (31)$$

where g is a locally bounded Carathéodory function, under assumption (h_1) and the following one:

There exists an integer $k \geq 1$ such that

$$\lambda_k \leq \liminf_{t \rightarrow 0} \frac{g(x, t)}{t} \leq \limsup_{t \rightarrow 0} \frac{g(x, t)}{t} < \lambda_{k+1}, \quad (32)$$

uniformly for a.e. $x \in \Omega$.

We point out that if the first inequality in (32) is strict, then Theorem 1.1 of [16] is a very special case of Theorem 4.1 written for $(\mathbf{P}_{A,K})$. For example, we require only that g be a locally bounded measurable function.

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