

**STOCHASTIC GAMES WITH RISK SENSITIVE  
PAY OFFS FOR N-PLAYERS**

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*Dedicated to Professor Sergio Campanato on his 70th birthday*

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## 1. Introduction.

In this paper we extend some of the results of the authors on stochastic differential games <sup>(1)</sup> to the case of risk sensitive payoffs. We consider that the stochastic process describing the system is stopped at the exit of a domain  $\mathcal{O}$  of  $\mathbb{R}^n$ . Like in the non stopped case (finite time horizon), the risk sensitive parameter cannot be arbitrary, see H. Nagai [10], A. Bensoussan - J. Frehse - H. Nagai [5] for the finite horizon case. On the other hand, the fact that we consider risk sensitive payoffs prevents to make use of discount factors in the cost functions. The system of Bellman equations related to the value functions has Dirichlet boundary conditions, and does not contain zero order terms. This complicates obtaining  $L^\infty$  bounds, since maximum principle arguments cannot be obtained easily. Other methods, already used by the authors to solve ergodic control problems apply conveniently to the present case.

Our approach to solve the stochastic differential games, taken as usual in the sense of Nash, is to prove regularity results for the solution of the system of Bellman equations. Then a standard verification argument can be used.

## 2. Setting of the Problem.

Let

$$(2.1) \quad \Omega = C^0([0, \infty); \mathbb{R}^n), \quad \mathcal{A} = \text{Borel } \sigma\text{-algebra on } \Omega.$$

The elements of  $\Omega$  are denoted by  $\omega = \omega(t)$ , and we equip  $\Omega$  with a probability measure  $P$  such that

$$(2.2) \quad \omega(t) \text{ is a standardized } n \text{ dimensional Wiener process.}$$

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<sup>(1)</sup> A. Bensoussan - J. Frehse [2], A. Bensoussan - J. Frehse [3].

We then set

$$(2.3) \quad \mathcal{F}^t = \sigma\{\omega(s), s \leq t, \omega \in \Omega\}.$$

A trajectory starting at  $x$ , is simply

$$(2.4) \quad x(t; \omega) = x + \omega(t).$$

We now consider  $N$  players, each of them acting through a control  $v_\nu(t)$ ,  $\nu = 1, \dots, N$ . We assume that

$$(2.5) \quad v_\nu(t) = (v_1(t), \dots, v_N(t)), \text{ adapted process with bounded values in } \mathbb{R}^{nN},$$

which we call an admissible control. Let also

$$(2.6) \quad g(x) \text{ be a measurable bounded function with values in } \mathbb{R}^n.$$

To a pair  $x, v(t)$ , where  $v(t)$  is a control vector as above, we associate the process

$$(2.7) \quad \beta_{x,v}(t) = g(x(t)) + \sum_{\mu} v_\mu(t)$$

and the probability  $P_{x,v}$  such that

$$(2.8) \quad \frac{dP_{x,v}}{dP} \Big|_{\mathcal{F}^t} = \exp \left\{ \int_0^t \beta_{x,v}(s) d\omega(s) - \frac{1}{2} \int_0^t |\beta_{x,v}(s)|^2 ds \right\}.$$

From the Girsanov theorem, if we introduce the process

$$(2.9) \quad w_{x,v}(t) = \omega(t) - \int_0^t \beta_{x,v}(s) ds,$$

then the system  $\Omega, \mathcal{A}, \mathcal{F}^t P_{x,v} w_{x,v}(t)$  forms a probability system in which  $w_{x,v}(t)$  is an  $\mathcal{F}^t$  standardized Wiener process. Note that from (2.9) one has

$$(2.10) \quad dx = (g(x(t)) + \sum_{\mu} v_\mu(t)) dt + dw_{x,v}(t), \quad x(0) = x.$$

Let now

$$(2.11) \quad \mathcal{O} = \text{open smooth bounded domain of } \mathbb{R}^n,$$

and let

$$(2.12) \quad \tau_x = \inf\{t \mid x(t) \notin \mathcal{O}\}.$$

We shall stop the process  $x(t)$  at the exit of the domain  $\mathcal{O}$ , and to save notation, we shall denote by  $x(t)$  also the stopped process. Let also

$$(2.13) \quad f_\nu(x) \text{ be a scalar measurable bounded function.}$$

In the sequel, we shall use the notation

$$(2.14) \quad v(t) = (v_\nu(t), v^\nu(t))$$

when  $v^\nu(t)$  represents all components which are different from  $v_\nu$ . We also shall use the notation

$$(2.15) \quad \bar{v}_\nu(t) = \sum_{\mu \neq \nu} v_\mu(t).$$

The payoff of player  $\nu$  is given by

$$(2.16) \quad \begin{aligned} Ju(x, v(\cdot)) &= Ju(x, v_\nu(\cdot), v^\nu(\cdot)) = \\ &= \frac{1}{\delta} \log E_{x,\nu} \exp \delta \left[ \int_0^{\tau_x} (f_\nu(x(t)) + \frac{1}{2} |v_\nu(t)|^2 + \theta v_\nu(t) \cdot \bar{v}_\nu(t)) dt \right] \end{aligned}$$

where  $\delta$  stands for the risk parameter. Note that as  $\delta$  tends to 0, this reduces to

$$E_{x,\nu} \left[ \int_0^{\tau_x} \left( f_\nu(x(t)) + \frac{1}{2} |v_\nu(t)|^2 + \theta v_\nu(t) \cdot \bar{v}_\nu(t) \right) dt \right]$$

which is the payoff considered in [4], except for the fact that we do not have a discount factor any more. If there is only one player, then the parameter  $\sigma$  is irrelevant.

A Nash point for the games defined by the functionals (2.16) is a control  $\hat{v}(\cdot)$  such that

$$(2.17) \quad J_\nu(x, \hat{v}_\nu, \hat{v}^\nu) \leq J_\nu(x, v_\nu, \hat{v}^\nu), \quad \forall v$$

for any admissible control  $v(\cdot)$ . See J. Nash [11], J. P. Aubin [1] for the concept of Nash point.

As indicated in the introduction, the method to prove the existence of a Nash point, will be to consider a system of Bellman equations for the value

functions of the game. This means, that, for a convenient control  $\hat{v}$ , possibly depending on  $x$  (the initial state), the functions

$$(2.18) \quad u_v(x) = J_v(x, \hat{v})$$

are the solutions of a system of partial differential equations. This system will allow to characterize optimal feedbacks for the  $N$  players. The proof of optimality will be performed by a verification argument. A key point is to obtain sufficient regularity properties for the value functions, otherwise, it is not possible to obtain feedbacks. Techniques of partial differential equation are instrumental in obtaining these necessary regularity properties.

### 3. Preliminaries.

#### 3.1. Lagrangians.

We introduce the Lagrangians by the following definition:

$$(3.1) \quad L_v(v, p) = \frac{1}{2}|v_v|^2 + \theta v_v \cdot \bar{v}_v + p_v \cdot \sum_{\mu} v_{\mu},$$

where

$$p = (p_1, \dots, p_N) \in \mathbb{R}^{nN},$$

$$v = (v_1, \dots, v_N) \in \mathbb{R}^{nN}$$

and, consistently, with the notation (2.15), we denote

$$(3.2) \quad \bar{v}_v = \sum_{\mu \neq v} v_{\mu},$$

$$(3.3) \quad \bar{p}_v = \sum_{\mu \neq v} p_{\mu}.$$

The first step is to consider, for a given  $p$ , a Nash point in  $v$  for the functions  $L_v(v, p)$ . Clearly, the following conditions must hold (by differentiation) for such a Nash point  $v(p)$ :

$$(3.4) \quad v_v(p) + \theta \bar{v}_v(p) + p_v = 0.$$

Provided

$$(3.5) \quad \theta \neq 1, \quad \theta \neq -\frac{1}{N-1},$$

it is easy to check that the system (3.4) has a unique solution given by the formulas

$$(3.6) \quad v_v(p) = \frac{\theta \sum_{\mu} p_{\mu}}{(1-\theta)(1+(N-1)\theta)} - \frac{p_v}{1-\theta}.$$

We note also the complementary formulas

$$(3.7) \quad \bar{v}_v(p) = \frac{-\sum_{\mu} p_{\mu}}{(1-\theta)(1+(N-1)\theta)} + \frac{p_v}{1-\theta}.$$

Then, we can define the quantities

$$(3.8) \quad L_v(p) = L_v(v(p), p).$$

It is useful to express also, from (3.6) and (3.7), the vectors  $p_v$  in terms of  $v(p)$  as follows:

$$(3.9) \quad p_v = -v_v(p) - \theta \bar{v}_v(p)$$

and also

$$(3.10) \quad \bar{p}_v = -(N-1)\theta v_v(p) + (-N\theta + 2\theta - 1)\bar{v}_v(p).$$

In particular, we can write

$$(3.11) \quad L_v(p) = -\frac{1}{2}|v_v(p)|^2 + p_v \cdot \bar{v}_v(p)$$

and also using (3.6), (3.7) in (3.11) after easy calculations we obtain

$$(3.12) \quad L_v(p) = -\frac{\theta^2}{2(1-\theta)^2(1+(N-1)\theta)^2} \left| \sum_{\mu} p_{\mu} \right|^2 + \frac{1-2\theta}{2(1-\theta)^2} |p_v|^2 + \frac{2\theta-1}{(1-\theta)^2(1+(N-1)\theta)} p_v \cdot \sum_{\mu} p_{\mu}.$$

### 3.2. More developments on Lagrangians.

We continue some useful developments on Lagrangians. We first note by summing up (3.12)

$$\begin{aligned}
 (3.13) \quad \sum_v L_v(p) &= \frac{\theta^2(3N-4) - 2\theta(N-3) - 2}{2(1-\theta)^2(1+(N-1)\theta)^2} \left| \sum_v p_v \right|^2 + \\
 &\quad + \frac{1-2\theta}{2(1-\theta)^2} \sum_v |p_v|^2 = \\
 &= \frac{-2(N-1)^2\theta^3 + (N^2 - 3N + 1)\theta^2 + 2\theta - 1}{2(1-\theta)^2(1+(N-1)\theta)^2} \sum_v |p_v|^2 + \\
 &\quad + 2 \frac{(3N-4)\theta^2 - 2(N-3)\theta - 2}{2(1-\theta)^2(1+(N-1)\theta)^2} \sum_{\substack{\mu, v \\ \mu \neq v}} p_\mu \cdot p_v.
 \end{aligned}$$

We shall be interested in guaranteeing the property

$$(3.14) \quad \sum_v L_v(p) \geq c_0 |p|^2, \quad \forall p, \quad c_0 > 0,$$

or, alternatively,

$$(3.15) \quad \sum_v L_v(p) \leq -c_1 |p|^2, \quad \forall p, \quad c_1 > 0.$$

From conditions on quadratic forms, in order to obtain (3.14) it will be enough to have

$$\begin{aligned}
 (3.16) \quad F(\theta) &= -(N-1)^2\theta^3 + (N^2 - 3N + 1)\frac{\theta^2}{2} + \theta - \frac{1}{2} - \\
 &\quad - (N-1) \left| \left( \frac{3N}{2} - 2 \right) \theta^2 - (N-3)\theta - 1 \right| > 0
 \end{aligned}$$

and

$$c_0 = \frac{F(\theta)}{(1-\theta)^2(1+(N-1)\theta)^2}.$$

Similarly to obtain (3.15), it will be sufficient to assert that

$$(3.17) \quad \hat{F}(\theta) = -(N-1)^2\theta^3 + (N^2 - 3N + 1)\frac{\theta^2}{2} + \theta - \frac{1}{2} +$$

$$+ (N-1) \left| \left( \frac{3N}{2} - 2 \right) \theta^2 - (N-3)\theta - 1 \right| < 0$$

and

$$c_1 = \frac{-\hat{F}(\theta)}{(1-\theta)^2(1+(N-1)\theta)^2}.$$

We shall characterize the values of  $\theta$  for which (3.16) and (3.17) hold. Considering the two possibilities for the absolute values, we are led to introducing the following two functions (after reduction of terms)

$$(3.18) \quad F_1(\theta) = -(N-1)^2\theta^3 + \frac{-2N^2 + 4N - 3}{2}\theta^2 + \theta(N^2 - 4N + 4) + N - \frac{3}{2},$$

$$(3.19) \quad F_2(\theta) = -(N-1)^2\theta^3 + \frac{4N^2 - 10N + 5}{2}\theta^2 - \theta(N^2 - 4N + 2) - N + \frac{1}{2}.$$

To make explicit the values of  $F(\theta)$  and  $\hat{F}(\theta)$ , we consider the two roots of

$$(3N-4)\frac{\theta^2}{2} - (N-3)\theta - 1,$$

namely

$$(3.20) \quad \theta_0 = \frac{N-3-\sqrt{N^2+1}}{3N-4}, \quad \theta_0 > -1 \text{ (for } N \geq 3), \quad \theta_0 < -1 \text{ (for } N = 2)$$

$$(3.21) \quad \theta'_0 = \frac{N-3+\sqrt{N^2+1}}{3N-4}, \quad \theta'_0 < 1,$$

and we have

$$(3.22) \quad \begin{aligned} F(\theta) &= F_1(\theta), & \text{if } \theta \leq \theta_0 \text{ or } \theta \geq \theta'_0, \\ F(\theta) &= F_2(\theta), & \text{if } \theta_0 \leq \theta \leq \theta'_0, \end{aligned}$$

$$(3.23) \quad \begin{aligned} \hat{F}(\theta) &= F_1(\theta), & \text{if } \theta_0 \leq \theta \leq \theta'_0, \\ \hat{F}(\theta) &= F_2(\theta), & \text{if } \theta \leq \theta_0 \text{ or } \theta \geq \theta'_0. \end{aligned}$$

Fortunately  $F_2(\theta)$  is quite simple. Indeed, from (3.19) it is easy to check that

$$(3.24) \quad F_2(\theta) = (\theta-1)^2 \left( -(N-1)^2\theta - N + \frac{1}{2} \right).$$

Let then

$$(3.25) \quad \bar{\theta} = -\frac{N - \frac{1}{2}}{(N - 1)^2},$$

and note that

$$(3.26) \quad \theta_0 < \bar{\theta} < 0 \quad (-1 < \theta_0 < \bar{\theta} \text{ for } N \geq 3), (\theta_0 < \bar{\theta} < -1 \text{ for } N = 2).$$

Clearly

$$(3.27) \quad \begin{aligned} F_2(\theta) &> 0 && \text{if } \theta \leq \bar{\theta}, \\ F_2(\theta) &\leq 0 && \text{if } \theta \geq \bar{\theta}, \end{aligned}$$

From the identity (3.22) for  $F(\theta)$ , we can immediately assert that

$$(3.28) \quad \begin{aligned} F(\theta) &> 0 && \text{for } \theta_0 \leq \theta < \bar{\theta}, \\ F(\theta) &\leq 0 && \text{for } \bar{\theta} \leq \theta \leq \theta'_0, \end{aligned}$$

and similarly from (3.23)

$$(3.29) \quad \begin{aligned} \hat{F}(\theta) &< 0 && \text{for } \theta \geq \theta'_0, \theta \neq 1, \\ \hat{F}(\theta) &> 0 && \text{for } \theta \leq \theta_0. \end{aligned}$$

To proceed, we must study the sign of  $F_1(\theta)$ , which is less simple. However the case  $N = 2$  is very simple and particular, since in this case one has

$$(3.30) \quad F_1(\theta) = (\theta + 1)^2 \left( -\theta + \frac{1}{2} \right)$$

and note that for  $N = 2$  we have

$$(3.31) \quad \theta_0 = \frac{-1 - 1\sqrt{5}}{2}, \quad \theta'_0 = \frac{-1 + \sqrt{5}}{2}, \quad \bar{\theta} = -\frac{3}{2},$$

and thus we can complete (3.28), (3.29) for  $N = 2$  easily

$$(3.32) \quad \begin{aligned} F(\theta) = F_1(\theta) &> 0 && \text{for } \theta \leq \theta_0, \\ F(\theta) = F_1(\theta) &< 0 && \text{for } \theta \geq \theta'_0, \end{aligned}$$

$$(3.33) \quad \begin{aligned} \hat{F}(\theta) = F_1(\theta) < 0 & \quad \text{for } \frac{1}{2} < \theta \leq \theta'_0, \\ \hat{F}(\theta) = F_1(\theta) \geq 0 & \quad \text{for } \theta_0 \leq \theta \leq \frac{1}{2}. \end{aligned}$$

Therefore we can state

$$(3.34) \quad \begin{aligned} \text{for } N = 2, F(\theta) > 0 & \text{ is equivalent to } \theta < -\frac{3}{2} = \bar{\theta}, \\ \hat{F}(\theta) < 0 & \text{ is equivalent to } \theta > \frac{1}{2} = \theta'', \quad \theta \neq 1. \end{aligned}$$

To study  $F_1(\theta)$ , for  $N \geq 3$ , we consider

$$F'_1(\theta) = -3(N-1)^2\theta^2 + (-2N^2 + 4N - 3)\theta + N^2 - 4N + 4$$

whose roots are  $\theta_1, \theta'_1$  given by the formulas

$$(3.35) \quad \theta_1 = \frac{-2N^2 + 4N - 3 - \sqrt{16N^4 - 88N^3 + 184N^2 - 168N + 57}}{6(N-1)^2}$$

$$(3.36) \quad \theta'_1 = \frac{-2N^2 + 4N - 3 + \sqrt{16N^4 - 88N^3 + 184N^2 - 168N + 57}}{6(N-1)^2}$$

and we have the configuration

$$(3.37) \quad -1 < \theta_1 < \theta_0 < \bar{\theta} < 0 < \theta'_1 < \theta'_0 < 1$$

and  $F'_1(\theta) < 0$  for  $\theta < \theta_1$ , and  $\theta > \theta'_1$ , whereas  $F'_1(\theta) \geq 0$  for  $\theta_1 \leq \theta \leq \theta'_1$ . Note also that

$$(3.38) \quad \begin{aligned} F_1(-\infty) = +\infty, \quad F_1(-1) \leq 0, \quad F_1(\theta_0) = F_2(\theta_0) > 0, \\ F_1(\theta'_0) = F_2(\theta'_0) < 0, \quad F_1(+\infty) = -\infty. \end{aligned}$$

From the sign of  $F'_1(\theta)$ , it also follows that

$$(3.39) \quad \begin{aligned} F_1(\theta_1) < 0, \quad \text{minimum of } F_1(\theta), \\ F_1(\theta'_1) > 0, \quad \text{maximum of } F_1(\theta). \end{aligned}$$

Therefore  $F_1(\theta)$  has three roots, two being negative,  $\theta', \theta''$ , and one positive  $\theta'''$  with the following location:

$$(3.40) \quad \theta' \leq -1, \quad \theta_1 < \theta'' < \theta_0, \quad \theta'_1 < \frac{1}{2} < \theta''' < \theta'_0$$

and we can conclude easily that

$$(3.41) \quad F(\theta) > 0 \text{ for } \theta < \theta' \text{ or } \theta'' < \theta < \bar{\theta},$$

$$(3.42) \quad \hat{F}(\theta) < 0 \text{ for } \theta > \theta''', \quad \theta \neq 1.$$

We then state the

**Lemma 3.1.** For  $N = 2$ , (3.14) holds whenever  $\theta < -\frac{3}{2}$ , and (3.15) holds when  $\theta > \frac{1}{2}$ ,  $\theta \neq 1$ . For  $N \geq 3$ , considering the numbers  $\theta'$ ,  $\theta''$ ,  $\theta'''$ ,  $\bar{\theta}$ , where  $\theta'$ ,  $\theta''$  are the two negative roots of  $F_1(\theta)$ ,  $\theta'''$  the positive root and  $\bar{\theta}$  is given by (3.25), the property (3.14) holds when  $\theta < \theta'$  or  $\theta'' < \theta < \bar{\theta}$ , and the property (3.15) holds when  $\theta > \theta'''$ ,  $\theta \neq 1$ .

**Remark 3.1.** In (3.5) we had excluded the values  $\theta = 1$ , and  $\theta = -\frac{1}{N-1}$ . Since  $\bar{\theta} < -\frac{1}{N-1} < 0$ , the value  $-\frac{1}{N-1}$  is out of the validity intervals defined in Lemma 3.1. The value  $\theta = 1$ , valid for (3.15) but not for (3.14) has to be excluded.

**Remark 3.2.** For  $N = 3$ , we have  $\theta' = -1$ ,  $\theta'' = \frac{-1-\sqrt{97}}{16}$ ,  $\theta''' = \frac{-1+\sqrt{97}}{16}$ ,  $\theta_1 = \frac{-9-\sqrt{129}}{24}$ ,  $\theta'_1 = \frac{-9+\sqrt{129}}{24}$ ,  $\theta_0 = -\frac{\sqrt{10}}{5}$ ,  $\theta'_0 = \frac{\sqrt{10}}{5}$ ,  $\bar{\theta} = -\frac{5}{8}$ .

### 3.3. Other properties.

From formula (3.12) we can deduce by using Young's inequality

$$(3.43) \quad L_v(p) \leq \frac{1-2\theta}{2\theta^2} |p_v|^2.$$

We proceed now with a different estimate. Note first that from (3.7) we can write

$$(3.44) \quad \bar{v}_v = \bar{v}_v(p) = \frac{(N-1)\theta p_v - \bar{p}_v}{(1-\theta)(1+(N-1)\theta)}.$$

By analogy with the formula (3.44) we consider a similar combination of the Lagrangians, namely

$$(3.45) \quad \tilde{L}_v(p) = (N-1)\theta L_v(p) - \sum_{\mu \neq v} L_\mu(p).$$

Consider (3.9) and (3.11) which yields

$$(3.46) \quad L_v(p) = -\frac{1}{2}|v_v|^2 - v_v \bar{v}_v - \theta |\bar{v}_v|^2 = -\frac{1}{2}|v_v + \bar{v}_v|^2 + \left(\frac{1}{2} - \theta\right) |\bar{v}_v|^2$$

hence as easily seen

$$(3.47) \quad \tilde{L}_v(p) = (N-1)\theta \left(\frac{1}{2} - \theta\right) |\bar{v}_v|^2 + \frac{1}{2}(N-1)(1-\theta) |v_v + \bar{v}_v|^2 -$$

$$\begin{aligned}
& - \left( \frac{1}{2} - \theta \right) \sum_{\mu \neq v} |\bar{v}_\mu|^2 = (N-1)\theta \left( \frac{1}{2} - \theta \right) |\bar{v}_v|^2 + \frac{1-\theta}{2(N-1)} \left| \sum_{\mu} \bar{v}_\mu \right|^2 - \\
& - \left( \frac{1}{2} - \theta \right) \sum_{\mu \neq v} |\bar{v}_\mu|^2 = \left[ (N-1)\theta \left( \frac{1}{2} - \theta \right) + \frac{1}{2} \frac{1-\theta}{N-1} \right] |\bar{v}_v|^2 + \\
& + \frac{1}{2} \frac{1-\theta}{N-1} \left| \sum_{\mu \neq v} \bar{v}_\mu \right|^2 + \frac{1-\theta}{N-1} \bar{v}_v \sum_{\mu \neq v} \bar{v}_\mu + \left( \theta - \frac{1}{2} \right) \sum_{\mu \neq v} |\bar{v}_\mu|^2.
\end{aligned}$$

Using

$$(3.48) \quad \left| \sum_{\mu \neq v} \bar{v}_\mu \right|^2 \leq (N-1) \sum_{\mu \neq v} |\bar{v}_\mu|^2$$

and assuming

$$(3.49) \quad \theta \geq \frac{1}{2}$$

we deduce

$$\begin{aligned}
(3.50) \quad \tilde{L}_v(p) & \geq \left[ (N-1)\theta \left( \frac{1}{2} - \theta \right) + \frac{1}{2} \frac{1-\theta}{N-1} \right] |\bar{v}_v|^2 + \frac{\theta}{2(N-1)} \left| \sum_{\mu \neq v} \bar{v}_\mu \right|^2 + \\
& + \frac{1-\theta}{N-1} \bar{v}_v \sum_{\mu \neq v} \bar{v}_\mu \geq -\frac{2\theta-1}{2\theta(N-1)} (\theta^2(N-1)^2 + \theta - 1) |\bar{v}_v|^2.
\end{aligned}$$

So we state the

**Lemma 3.2.** *When  $\theta \geq \frac{1}{2}$  one has the property*

$$(3.51) \quad \tilde{L}_v(p) \geq -k |\bar{v}_v|^2.$$

In the sequel we shall use (3.43) and (3.14) together when  $\theta < 0$  ( $\theta$  satisfying the conditions of Lemma 3.1) and (3.15), (3.51) together when  $\theta > 0$  (in fact  $\theta > \theta''' > \frac{1}{2}$ ,  $\theta \neq 1$ ).

### 3.4. Taking account of the risk factor.

The risk factor will imply a perturbation of the Lagrangian, namely  $L_\nu(p)$  has to be replaced for

$$(3.52) \quad M_\nu(p) = L_\nu(p) + \frac{\delta}{2}|p_\nu|^2.$$

The property (3.43) is clearly unchanged

$$(3.53) \quad M_\nu(p) \leq \left( \frac{1-2\theta}{2\theta^2} + \frac{\delta}{2} \right) |p_\nu|^2.$$

The property (3.14) is improved, since

$$(3.54) \quad \sum_\nu M_\nu(p) = \sum_\nu L_\nu(p) + \frac{\delta}{2}|p|^2$$

and if (3.14) holds, a fortiori

$$(3.55) \quad \sum_\nu M_\nu(p) \geq c_0|p|^2.$$

Since the risk factor here helps, it modifies the discussion on  $\theta$ . From formula (3.13), what matters now is to have

$$(3.56) \quad F_\delta(\theta) = \frac{\delta}{2}(1-\theta)^2(1+(N-1)\theta)^2 - (N-1)^2\theta^3 + \\ + (N^2 - 3N + 1)\frac{\theta^2}{2} + \theta - \frac{1}{2} - (N-1) \left| \left( \frac{3N}{2} - 2 \right) \theta^2 - (N-3)\theta - 1 \right| > 0.$$

Define

$$(3.57) \quad F_{1\delta}(\theta) = F_1(\theta) + \frac{\delta}{2}(1-\theta)^2(1+(N-1)\theta)^2,$$

$$(3.58) \quad F_{2\delta}(\theta) = F_2(\theta) + \frac{\delta}{2}(1-\theta)^2(1+(N-1)\theta)^2.$$

We have

$$(3.59) \quad F_\delta(\theta) = F_{1\delta}(\theta) \quad \text{if } \theta \leq \theta_0 \text{ or } \theta \geq \theta'_0,$$

$$F_\delta(\theta) = F_{2\delta}(\theta) \quad \text{if } \theta_0 \leq \theta \leq \theta'_0.$$

The function  $F_{2\delta}(\theta)$  is easy to compute (using (3.24))

$$(3.60) \quad F_{2\delta}(\theta) = \frac{(\theta - 1)^2}{2} [\delta(N-1)^2\theta^2 + 2(N-1)\theta(\delta - (N-1)) - 2N + 1 + \delta]$$

hence the two roots not equal to 1 are

$$(3.61) \quad \bar{\theta}_\delta = \frac{1 - \frac{\delta}{N-1} - \sqrt{1 + \frac{\delta}{(N-1)^2}}}{\delta} \quad \bar{\theta}'_\delta = \frac{1 - \frac{\delta}{N-1} + \sqrt{1 + \frac{\delta}{(N-1)^2}}}{\delta}$$

and  $\bar{\theta} < \bar{\theta}_\delta$ . Therefore

$$(3.62) \quad \begin{aligned} F_{2\delta}(\theta) &> 0 && \text{if } \theta < \bar{\theta}_\delta \text{ or } \theta > \bar{\theta}'_\delta, \quad \theta \neq 1, \\ F_{2\delta}(\theta) &\leq 0 && \text{if } \bar{\theta}_\delta \leq \theta \leq \bar{\theta}'_\delta. \end{aligned}$$

We need next to study  $F_{1\delta}(\theta)$ . We assume  $N \geq 3$ . Note that

$$(3.63) \quad F'_{1\delta}(\theta) = F'_1(\theta) + \delta(\theta - 1)(1 + (N-1)\theta)(2\theta(N-1) - (N-2)).$$

For  $\theta < -\frac{1}{N-1}$ , we have  $F'_{1\delta}(\theta) < F'_1(\theta)$ . Hence

$$F'_{1\delta}(\theta) < 0 \quad \text{for } \theta \leq \theta_1.$$

Noting that  $\theta'_1 < \frac{N-2}{2(N-1)} < \theta'_0$ , we have also

$$F'_{1\delta}(\theta) < 0 \quad \text{for } \frac{N-2}{2(N-1)} \leq \theta \leq 1.$$

Similarly, since  $\bar{\theta} < -\frac{1}{N-1}$ , one has also

$$F'_{1\delta}(\theta) > 0 \quad \text{for } -\frac{1}{N-1} \leq \theta \leq \theta'_1.$$

Furthermore  $F'_{1\delta}(\theta) > 0$  for  $\theta$  sufficiently larger  $> 1$ . Therefore  $F'_{1\delta}(\theta)$  has necessarily three roots, which we denote  $\theta_{1\delta}$ ,  $\theta'_{1\delta}$ ,  $\theta''_{1\delta}$ . We can also assert that

$$(3.64) \quad \begin{aligned} \theta_1 &< \theta_{1\delta} < -\frac{1}{N-1} \\ \theta'_1 &< \theta'_{1\delta} < \frac{N-2}{2(N-1)}, \quad \theta''_{1\delta} > 1. \end{aligned}$$

Moreover as  $\delta \rightarrow 0$ ,  $\theta_{1\delta} \rightarrow \theta_1$ ,  $\theta'_{1\delta} \rightarrow \theta'_1$ ,  $\theta''_{1\delta} \rightarrow +\infty$ , and as  $\delta \rightarrow \infty$ ,  $\theta_{1\delta} \rightarrow -\frac{1}{N-1}$ ,  $\theta'_{1\delta} \rightarrow \frac{N-2}{2(N-1)}$ ,  $\theta''_{1\delta} \rightarrow 1$ . Hence  $F_{1\delta}(\theta)$  has two local minima,  $\theta_{1\delta}$  and  $\theta''_{1\delta}$ , and one local maximum  $\theta'_{1\delta}$ . Note the following properties

$$(3.65) \quad \begin{aligned} F_{1\delta}(\theta) &> 0, \quad \theta \leq \theta' \quad \text{and} \quad \theta'' \leq \theta \leq \theta''', \\ F_{1\delta}(1) &= F_1(1) = -N^2 + N < 0, \\ F_{1\delta}(-\infty) &= F_{1\delta}(+\infty) = +\infty. \end{aligned}$$

Therefore the value at the local minimum  $\theta''_{1\delta}$  is strictly negative, and thus  $F_{1\delta}$  has two positive roots  $\theta'''_{1\delta}$ ,  $\theta''_{1\delta}$ . Necessarily, since  $F_{1\delta}(\theta''') > 0$ , we have

$$(3.66) \quad \theta''' < \theta'''_{1\delta} < 1 < \theta'''_{2\delta}.$$

The value at the local minimum  $\theta_{1\delta}$  is not necessarily negative. It is so if  $\delta$  is sufficiently small, since  $\theta_{1\delta}$  is close to  $\theta_1$ , and  $F_{1\delta}(\theta_{1\delta}) \sim F_1(\theta_1) < 0$ . In that case there will be two negative roots of  $F_{1\delta}(\theta)$ , denoted by  $\theta'_\delta$ ,  $\theta''_\delta$ , and from (3.65) necessarily one has

$$(3.67) \quad \theta' < \theta'_\delta < \theta_{1\delta} < \theta''_\delta < \theta''.$$

So

$$(3.68) \quad F_{1\delta} > 0 \text{ for } \theta \in (-\infty, \theta'_\delta), \quad \theta \in (\theta''_\delta, \theta'''_{1\delta}), \quad \theta > \theta'''_{2\delta},$$

and the interval  $\theta'_\delta, \theta''_\delta$  may be void.

For  $\delta = 0$ , we have  $\theta'_\delta = \theta'$ ,  $\theta''_\delta = \theta''$ ,  $\theta'''_{1\delta} = \theta'''$ ,  $\theta'''_{2\delta} = +\infty$  and  $\bar{\theta}_\delta = \bar{\theta}$ ,  $\theta'_\delta = +\infty$ . We recover the situation of paragraph 3.2. For  $\delta = +\infty$ , the numbers  $\theta'_\delta, \theta''_\delta$  do not exist and  $\theta'''_{1\delta} = \theta'''_{2\delta} = 1$ , hence  $F_{1\delta}(\theta) > 0, \forall \theta, \theta \neq 1$ . Also  $\bar{\theta}_\delta = \bar{\theta}_\delta = -\frac{1}{N-1}$ , and  $F_{2\delta}(\theta) > 0, \forall \theta \neq 1, \theta \neq -\frac{1}{N-1}$ .

We shall also use the property

$$(3.69) \quad \begin{aligned} \text{If } \bar{\theta}'_\delta \leq \bar{\theta}'_0 \text{ then } \theta'_0 &\leq \theta'''_{1\delta} \text{ (equality only when } \bar{\theta}'_\delta = \bar{\theta}'_0) \\ \text{If } \bar{\theta}'_\delta > \bar{\theta}'_0 \text{ then } \theta'_0 &> \theta'''_{1\delta}. \end{aligned}$$

Indeed, in the first case we have by definition of  $\bar{\theta}'_\delta$ ,  $F_{2\delta}(\theta'_0) \geq 0$ , hence  $F_{1\delta}(\theta'_0) = F_{2\delta}(\theta'_0) \geq 0$ . Now, if  $\theta'''_{1\delta} < \theta'_0$ , we have  $F_{1\delta}(\theta'_0) < 0$ , which leads to a contradiction.

The second case is proven in a similar way.

Collecting results, thanks to (3.62), (3.68) and the definition (3.59) as well as (3.69) we get

(3.70)

$$F_\delta(\theta) > 0 \text{ for } \theta \in (-\infty, \theta'_\delta), (\theta''_\delta, \bar{\theta}_\delta), (\bar{\theta}'_\delta, \theta'''_{1\delta}), (\theta'''_{2\delta}, \infty), \text{ if } \bar{\theta}'_\delta < \theta'_0,$$

$$F_\delta(\theta) > 0 \text{ for } \theta \in (-\infty, \theta'_\delta), (\theta''_\delta, \bar{\theta}_\delta), (\theta'''_{2\delta}, \infty), \text{ if } \bar{\theta}_\delta \geq \theta'_0.$$

For  $\delta = 0$  this yields  $F_\delta(\theta) > 0$ , for  $\theta < \bar{\theta}$ , and if  $\delta = +\infty$ , we get  $F_\delta(\theta) > 0 \forall \theta, \theta \neq 1, \theta \neq -\frac{1}{N-1}$ . Finally in the case  $N = 2$ , we have

$$F_{2\delta}(\theta) = \frac{(\theta + 1)}{2} [\delta(1 - \theta)^2 + 1 - 2\theta],$$

$$F_{1\delta}(\theta) = \frac{(\theta + 1)}{2} [\delta(1 + \theta)^2 - 2\theta - 3]$$

hence

$$\theta' = \theta''_\delta = -1,$$

$$\theta'''_{1\delta} = \frac{1 + \delta - \sqrt{1 + \delta}}{\delta}, \quad \theta'''_{2\delta} = \frac{1 + \delta + \sqrt{1 + \delta}}{\delta}$$

$$\bar{\theta}_\delta = \frac{1 - \delta - \sqrt{1 - \delta}}{\delta}, \quad \bar{\theta}'_\delta = \frac{1 - \delta + \sqrt{1 + \delta}}{\delta}.$$

We now examine how to assert

$$(3.71) \quad \sum_v M_v(p) \leq -c_1 |p|^2$$

and

$$(3.72) \quad \tilde{M}_v(p) \geq -k |\bar{v}_v|^2,$$

where  $\tilde{M}_v(p)$  is defined analogously to  $\tilde{L}_v(p)$ , see (3.45). Here the risk factor is not helping, so  $\delta$  cannot be too large.

Let us investigate the conditions on  $\theta$ . We must obtain  $\hat{F}_\delta(\theta) < 0$ , with

$$(3.73) \quad \hat{F}_\delta(\theta) = \begin{cases} F_{1\delta}(\theta) & \text{if } \theta_0 \leq \theta \leq \theta'_0 \\ F_{2\delta}(\theta) & \text{if } \theta \leq \theta_0 \text{ or } \theta \geq \theta'_0. \end{cases}$$

We may assert, using (3.62), (3.68), (3.69), and the definition (3.73), that

$$(3.74) \quad \hat{F}_\delta(\theta) \geq 0, \quad \forall \theta, \text{ when } \bar{\theta}'_\delta \leq \theta'_0 \text{ so there is no validity interval}$$

$$(3.75) \quad \hat{F}_\delta(\theta) < 0 \text{ if } \theta \in (\theta''_{1\delta}, \bar{\theta}'_\delta), \text{ when } \bar{\theta}'_\delta > \theta'_0.$$

For  $\delta = 0$ , we get  $(\theta''', \infty)$ . For  $\delta = \infty$ , there is no validity interval.

Let us now check (3.72). A tedious but easy calculation leads to the formula

$$(3.76) \quad (N-1)\theta|p_v|^2 - \sum_{\mu \neq v} |p_\mu|^2 = |\bar{v}_v|^2 \left\{ \frac{1}{N-1} + \theta(\theta-1)(\theta(N-1)-N+3) \right\} - \\ - \frac{(\theta-1)}{N-1} \left| \sum_{\mu \neq v} \bar{v}_\mu \right|^2 - (\theta-1)^2 \sum_{\mu \neq v} |\bar{v}_\mu|^2 - 2\theta(1-\theta)\bar{v}_v \sum_{\mu \neq v} \bar{v}_\mu$$

therefore

$$(3.77) \quad \tilde{M}_v(p) = |\bar{v}_v|^2 \left\{ (N-1)\theta \left( \frac{1}{2} - \theta \right) + \frac{1}{2} \frac{1-\theta}{N-1} + \right. \\ \left. + \frac{\delta}{2} \left[ \theta(\theta-1)(\theta(N-1)-N+3) + \frac{1}{N-1} \right] \right\} + \\ + \frac{|\sum_{\mu \neq v} \bar{v}_\mu|^2}{2(N-1)} (1-\theta)(1+\delta) + (1-\theta) \left( \frac{1}{N-1} - \delta\theta \right) \bar{v}_v \sum_{\mu \neq v} \bar{v}_\mu + \\ + \left( \left( \theta - \frac{1}{2} \right) - \frac{\delta}{2} (\theta-1)^2 \right) \sum_{\mu \neq v} |\bar{v}_\mu|^2.$$

Assume that

$$(3.78) \quad \theta - \frac{1}{2} - \frac{\delta}{2} (\theta-1)^2 > 0$$

and using (3.48) we get finally the estimate

$$(3.79) \quad \tilde{M}_v(p) \geq |\bar{v}_v|^2 \left\{ (N-1)\theta \left( \frac{1}{2} - \theta \right) + \frac{1}{2} \frac{1-\theta}{N-1} + \right. \\ \left. + \frac{\delta}{2} \left[ \theta(\theta-1)(\theta(N-1)-N+3) + \frac{1}{N-1} \right] \right\} + \\ + (1-\theta) \left( \frac{1}{N-1} - \delta\theta \right) \bar{v}_v \sum_{\mu \neq v} \bar{v}_\mu + \frac{\theta(1-\delta(\theta-1))}{2(N-1)} \left| \sum_{\mu \neq v} \bar{v}_\mu \right|^2$$

and if we also assume

$$(3.80) \quad 1 - \delta(\theta-1) > 0$$

we deduce from (3.79) the estimate (3.72).

Collecting results we can state the

**Lemma 3.3.** *If  $\theta$  belongs to the validity intervals defined in (3.70), then we have (3.53), (3.55). On the other hand, if  $\theta'_0 < \bar{\theta}'_0$  and  $\theta \in (\theta'''_{1\delta}, \bar{\theta}'_{1\delta})$  and satisfies the properties (3.78), (3.80), then (3.71), (3.72) are satisfied.*

#### 4. Nonlinear system of partial differential equations.

##### 4.1. Setting of the problem.

Here we consider the following system of equations:

$$(4.1) \quad \begin{aligned} -\frac{1}{2}\Delta u_\nu &= H_\nu(x, Du) \\ u_\nu|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

Firstly, the functions  $H_\nu(x, p)$  satisfy

$$(4.2) \quad H_\nu(x, p) \text{ are Caratheodory functions.}$$

We shall make an important use of linear manipulations on the equations (4.1). Consider an  $N \times N$  matrix  $\Gamma$ , which is invertible, and define

$$(4.3) \quad H^\Gamma(x, p) = \Gamma H(x, \Gamma^{-1}p),$$

where  $H(x, p)$  represents the vector  $H_\nu(x, p)$ . Setting

$$(4.4) \quad z = \Gamma u,$$

then we see that  $z$  is the solution of

$$(4.5) \quad \begin{aligned} -\frac{1}{2}\Delta z_\nu &= H^\Gamma_\nu(x, Dz) \\ z_\nu|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

So our original problem (4.1) is imbedded in a family of equivalent problems, indexed by the transformation  $\Gamma$ . All matrices  $\Gamma$  to be considered will be *invertible*, so we shall not mention it explicitly.

A matrix  $\Gamma$  satisfies the maximum principle if

$$(4.6) \quad \Gamma u \geq 0 \Rightarrow u \geq 0.$$

We begin by starting two alternative sets of assumptions:

$$(4.7) \quad \sum_{\nu} H_{\nu}(x, p) \geq -\lambda.$$

There exists a matrix  $\Gamma$  which satisfies the maximum principle and

$$(4.8) \quad H_{\nu}^{\Gamma}(x, p) \leq \lambda_{\nu} + \lambda_{\nu}^0 |p_{\nu}|^2, \quad \lambda_{\nu}, \lambda_{\nu}^0 \text{ not too large}$$

or

$$(4.9) \quad \sum_{\nu} H_{\nu}(x, p) \leq \lambda.$$

There exists a matrix  $\Gamma$  which satisfies the maximum principle and

$$(4.10) \quad H_{\nu}^{\Gamma}(x, p) \geq -\lambda_{\nu} - \lambda_{\nu}^0 |p_{\nu}|^2, \quad \lambda_{\nu}, \lambda_{\nu}^0 \text{ not too large.}$$

We furthermore assume

$$(4.11) \quad \text{There exists a matrix } \Gamma \text{ such that} \\ H_{\nu}^{\Gamma}(x, p) = Q(x, p) \cdot p_{\nu} + H_{\nu}^0(x, p)$$

with

$$(4.12) \quad |Q(x, p)| \leq k + K|p|,$$

$$(4.13) \quad |H_{\nu}^0(x, p)| \leq k_{\nu} + K_{\nu} \sum_{\mu \leq \nu} |p_{\mu}|^2.$$

**Remark 4.1.** If we pick  $\nu = N$  in (4.13) we obtain

$$|H_N^0(x, p)| \leq k_N + K_N |p|^2$$

which is a general quadratic growth assumption. So if  $H(x, p)$  has a general quadratic growth, it is sufficient to check (4.11), (4.12), (4.13) for  $\nu = 1, \dots, N - 1$ . We may define

$$(4.14) \quad H_N^0(x, p) = H_N^{\Gamma}(x, p) - Q(x, p) \cdot p_N$$

and (4.11), (4.13) will be satisfied automatically.

Our objective is to prove the

**Theorem 4.1.** *We assume that the functions  $H_\nu(x, p)$  satisfy (4.2), (4.11), (4.12), (4.13) and one or the other of the two sets of assumptions (4.7), (4.8) or (4.9), (4.10). Then there exists a solution of (4.1) which is in  $W^{2,s}(\mathcal{O})$ ,  $\forall s$  such that  $2 \leq s < \infty$ .*

The proof will be done by explaining how to obtain an a priori estimates first, then an approximation argument will be used. We shall consider the Green function associated with any point  $\xi \in \mathcal{O}$ , corresponding to the operator  $-\frac{1}{2}\Delta$ , called  $G^\xi$ . It is the solution of the equation (written formally)

$$(4.15) \quad \begin{aligned} -\frac{1}{2}\Delta G^\xi &= \delta(x - z) \\ G^\xi|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

The Green function is positive and satisfies the following estimates

$$(4.16) \quad \|G^\xi\|_{L^q(\mathcal{O})} \leq C, \quad \forall \xi, \quad 1 \leq q < \frac{n}{n-2}$$

$$(4.17) \quad \|G^\xi\|_{W_0^{1,r}(\mathcal{O})} \leq C, \quad \forall \xi, \quad 1 \leq r < \frac{n}{n-1}.$$

We shall denote by  $\|G\|_{L^q}$ ,  $\|G\|_{W^{1,r}}$  the bounds on the right-hand side of (4.16), (4.17).

#### 4.2. $L^\infty$ a priori estimate.

We assume (4.3), (4.4). We shall indicate briefly the changes which are necessary when (4.5), (4.6) apply. Summing up the equations (4.1) yields

$$-\frac{1}{2}\Delta \sum_\nu u_\nu = \sum_\nu H_\nu(x, Du) \geq -\lambda.$$

We test with  $(\sum_\nu u_\nu)^- G^\xi$ , hence we get

$$\frac{1}{2} \int_{\mathcal{O}} D \sum_\nu u_\nu D \left( \left( \sum_\nu u_\nu \right)^- G^\xi \right) dx \geq -\lambda \int_{\mathcal{O}} \left( \sum_\nu u_\nu \right)^- G^\xi dx$$

hence as easily seen

$$\frac{1}{4} \int_{\mathcal{O}} D \left( \left( \sum_\nu u_\nu \right)^- \right)^2 DG^\xi dx + \frac{1}{2} \int_{\mathcal{O}} \left| D \left( \sum_\nu u_\nu \right)^- \right|^2 G^\xi dx \leq$$

$$\leq \lambda \int_{\mathcal{O}} \left( \sum_{\nu} u_{\nu} \right)^{-} G^{\xi} dx.$$

From the definition of the Green function we obtain

$$\frac{1}{2} \left( \left( \sum_{\nu} u_{\nu} \right)^{-}(\xi) \right)^2 \leq \lambda \int_{\mathcal{O}} \left( \sum_{\nu} u_{\nu} \right)^{-} G^{\xi} dx.$$

Suppose  $\xi$  is a point where  $\left( \sum_{\nu} u_{\nu} \right)^{-}$  reaches a positive maximum (necessarily in  $\mathcal{O}$ ), then we get

$$\left\| \left( \sum_{\nu} u_{\nu} \right)^{-} \right\|_{\infty} \leq 2\lambda \int_{\mathcal{O}} G^{\xi} dx \leq C.$$

Therefore we have proven the first  $L^{\infty}$  estimate

$$(4.18) \quad \sum_{\nu} u_{\nu} \geq -c.$$

We consider now the matrix  $\Gamma$  intervening in the assumption (4.8) and set

$$\tilde{u} = \Gamma u.$$

From (4.5) we know that

$$(4.19) \quad \begin{aligned} -\frac{1}{2} \Delta \tilde{u}_{\nu} &= H_{\nu}^{\Gamma}(x, D\tilde{u}) \\ \tilde{u}_{\nu}|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

Let us set

$$(4.20) \quad E_{\nu} = \exp 2\lambda_{\nu}^0 \tilde{u}_{\nu},$$

then

$$-\frac{1}{2} \Delta E_{\nu} = -E_{\nu} [2(\lambda_{\nu}^0)^2 |D\tilde{u}_{\nu}|^2 + \lambda_{\nu}^0 \Delta \tilde{u}_{\nu}]$$

and from (4.19) and the property (4.8) this yields

$$-\frac{1}{2} \Delta E_{\nu} \leq 2\lambda_{\nu} \lambda_{\nu}^0 E_{\nu}.$$

Using  $E_\nu G^\xi$  as a test function we get

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{O}} |DE_\nu|^2 G^\xi dx + \frac{1}{4} \int_{\mathcal{O}} D(E_\nu^2 - 1) DG^\xi dx &\leq \\ &\leq 2\lambda_\nu \lambda_\nu^0 \int_{\mathcal{O}} E_\nu^2 G^\xi dx \end{aligned}$$

hence (noting that  $E_\nu^2 - 1$  vanishes on  $\partial\mathcal{O}$ )

$$\frac{1}{2} (E_\nu^2(\xi) - 1) \leq 2\lambda_\nu \lambda_\nu^0 \int_{\mathcal{O}} E_\nu^2 G^\xi dx$$

$$(4.21) \quad E_\nu^2(\xi) \leq 1 + 4\lambda_\nu \lambda_\nu^0 \int_{\mathcal{O}} E_\nu^2 G^\xi dx .$$

If  $\xi$  is chosen to be the maximum of  $\tilde{u}_\nu$ , assumed to be positive, hence  $\xi \in \partial\mathcal{O}$ , we deduce from (4.21)

$$\|E_\nu^2\|_\infty \leq 1 + 4\lambda_\nu \lambda_\nu^0 \|E_\nu^2\|_\infty \|G\|_{L^1}$$

and using the assumption (4.8), provided that  $\lambda_\nu \lambda_\nu^0$  is sufficiently small so that

$$(4.22) \quad 4\lambda_\nu \lambda_\nu^0 \|G\|_{L^1} < 1$$

we obtain

$$(4.23) \quad \|E_\nu^2\|_\infty \leq \frac{1}{1 - 4\lambda_\nu \lambda_\nu^0 \|G\|_{L^1}}$$

hence also

$$(4.24) \quad \tilde{u}_\nu \leq C .$$

Since  $\Gamma$  satisfies the maximum principle, we get also for the original functions  $u_\nu$

$$(4.25) \quad u_\nu \leq c$$

which together with (4.18) implies

$$(4.26) \quad \|u_\nu\|_{L^\infty} \leq c .$$

Let us indicate the changes to be performed when (4.9), (4.10) apply. We test with  $(\sum_\nu u_\nu)^+ G^\xi$  to obtain first, thanks to (4.9)

$$(4.27) \quad \sum_\nu u_\nu \leq c.$$

Introduce again the functions

$$\tilde{u} = \Gamma u$$

where  $\Gamma$  refers to the matrix intervening (4.10).

We set this time

$$(4.28) \quad E_\nu = \exp(-2\lambda_\nu^0 \tilde{u}_\nu)$$

and perform computation similar to those for obtaining (4.21). Making use of (4.22), thanks to assumption (4.10) we deduce

$$\|E_\nu^2\|_\infty \leq c$$

hence

$$(4.29) \quad \tilde{u}_\nu \geq -c$$

and since  $\Gamma$  satisfies the maximum principle, this implies

$$(4.30) \quad u_\nu \geq c$$

which together with (4.27) means again

$$(4.31) \quad \|u_\nu\|_\infty \leq c.$$

### 4.3. $H_0^1$ estimate.

To obtain the  $H_0^1$  estimate, we shall make use of the special structure (4.11), (4.12), (4.13). We omit this notation  $\Gamma$ , to simplify the writing and by virtue of the  $L^\infty$  estimate, we have

$$(4.32) \quad |u_\nu(x)| \leq \rho.$$

To obtain an a priori estimate for  $H_0^1$ , one uses a specific test function. Set

$$\beta(s) = e^s - s - 1$$

and

$$F = \prod_{\nu=1}^N \exp(\beta(\gamma_\nu u_\nu))$$

where  $\gamma$  is a positive constant to be defined later. We have

$$DF = F \sum_{\nu=1}^N \gamma_\nu \beta'(\gamma_\nu u_\nu) Du_\nu.$$

We test (4.1) with  $F \gamma_\nu \beta'(\gamma_\nu u_\nu)$ , which vanishes on the boundary, integrate by parts and add up. We get

$$\begin{aligned} & \sum_{\nu} \frac{1}{2} \int_{\mathcal{O}} \gamma_\nu^2 |Du_\nu|^2 e^{\gamma_\nu u_\nu} F dx + \frac{1}{2} \int_{\mathcal{O}} \frac{|DF|^2}{F} dx = \\ & = \int_{\mathcal{O}} Q \cdot DF dx + \int_{\mathcal{O}} \sum_{\nu} \gamma_\nu H_\nu^0(Du) F (e^{\gamma_\nu u_\nu} - 1) dx \end{aligned}$$

hence also

$$(4.33) \quad \begin{aligned} \sum_{\nu} \frac{1}{2} \int_{\mathcal{O}} \gamma_\nu^2 |Du_\nu|^2 e^{\gamma_\nu u_\nu} F dx & \leq \frac{1}{2} \int_{\mathcal{O}} F Q \cdot Q dx + \\ & + \int_{\mathcal{O}} \sum_{\nu} \gamma_\nu H_\nu^0(Du) F (e^{\gamma_\nu u_\nu} - 1) dx. \end{aligned}$$

In order to get comparable terms on both sides, we introduce the function

$$(4.34) \quad X = \prod_{\nu=1}^N (\exp \beta(\gamma_\nu u_\nu) + \exp \beta(-\gamma_\nu u_\nu))$$

and the related quantities

$$\begin{aligned} X_\nu &= X \frac{e^{\gamma_\nu u_\nu} \exp \beta(\gamma_\nu u_\nu) + e^{-\gamma_\nu u_\nu} \exp \beta(-\gamma_\nu u_\nu)}{\exp \beta(\gamma_\nu u_\nu) + \exp \beta(-\gamma_\nu u_\nu)}, \\ \tilde{X}_\nu &= X \frac{(e^{\gamma_\nu u_\nu} - 1) \exp \beta(\gamma_\nu u_\nu) - (e^{-\gamma_\nu u_\nu} - 1) \exp \beta(-\gamma_\nu u_\nu)}{\exp \beta(\gamma_\nu u_\nu) + \exp \beta(-\gamma_\nu u_\nu)}. \end{aligned}$$

We have the inequalities

$$2^N \leq X \leq X_\nu \leq X e^{\gamma_\nu |u_\nu|},$$

$$|\tilde{X}_v| \leq X_v.$$

Applying the relations (4.33) with  $\gamma_v$  changed one by one into  $-\gamma_v$ , and summing up the  $2^N$  relations obtained in this way, we get the inequality

$$\begin{aligned} \frac{1}{2} \sum_v \int_{\mathcal{O}} \gamma_v^2 |Du_v|^2 X_v dx &\leq \frac{1}{2} \int_{\mathcal{O}} X Q \cdot Q dx + \\ &+ \int_{\mathcal{O}} \sum_v \gamma_v H_v^0(Du) \tilde{X}_v dx \end{aligned}$$

hence

$$\begin{aligned} \frac{1}{2} \sum_v \int_{\mathcal{O}} \gamma_v^2 |Du_v|^2 X_v dx &\leq \frac{1}{2} \int_{\mathcal{O}} X Q \cdot Q dx + \int_{\mathcal{O}} \sum_v \gamma_v |H_v^0(Du)| X_v dx \leq \\ &\leq \frac{1}{2} \int_{\mathcal{O}} X Q \cdot Q dx + \int_{\mathcal{O}} \sum_v \gamma_v (k_v + K_v |Du_v|^2) X_v dx + \\ &+ \int_{\mathcal{O}} \sum_v |Du_v|^2 \sum_{\mu > v} \gamma_{\mu} K_{\mu} X_{\mu} dx \leq \\ &\leq \int_{\mathcal{O}} k^2 X dx + K^2 \sum_v \int_{\mathcal{O}} X_v |Du_v|^2 dx + \sum_v \gamma_v \int_{\mathcal{O}} (k_v + K_v |Du_v|^2) X_v dx + \\ &+ \int_{\mathcal{O}} \sum_v |Du_v|^2 \sum_{\mu > v} \gamma_{\mu} K_{\mu} X_{\mu} dx. \end{aligned}$$

We obtain

$$\begin{aligned} \sum_v \int_{\mathcal{O}} |Du_v|^2 X_v \left[ \frac{1}{2} \gamma_v^2 - K^2 - \gamma_v K_v \right] dx &\leq \int_{\mathcal{O}} (k^2 X + \sum_v \gamma_v k_v X_v) dx + \\ &+ \sum_v \int_{\mathcal{O}} |Du_v|^2 \sum_{\mu > v} \gamma_{\mu} K_{\mu} X_{\mu} dx. \end{aligned}$$

Finally

$$\sum_v \int_{\mathcal{O}} X |Du_v|^2 \left[ \frac{1}{2} \gamma_v^2 - K^2 - \gamma_v K_v - \sum_{\mu > v} \gamma_{\mu} K_{\mu} e^{\rho \gamma_{\mu}} \right] dx \leq$$

$$\leq \int_{\mathcal{O}} X(k^2 + \sum_{\nu} \gamma_{\nu} k_{\nu} e^{\rho \gamma_{\nu}}) dx$$

with  $\rho = \|u\|_{\infty}$ . Therefore if we choose the constants  $\gamma_{\nu}$  so that

$$(4.35) \quad \frac{1}{2} \gamma_{\nu}^2 - K^2 - \gamma_{\nu} K_{\nu} - \sum_{\mu > \nu} \gamma_{\mu} e^{\rho \gamma_{\mu}} > 0$$

we get

$$(4.36) \quad \int_{\mathcal{O}} |Du|^2 dx \leq K_0(\rho).$$

It is possible to choose the constants  $\gamma_{\nu}$  in order to fulfill (4.35). This can be done backwards, starting with  $\gamma_N$ .

#### 4.4. $C^{\delta}$ and $W^{1,p}$ estimates.

The special structure permits to obtain additional estimates in  $C^{\delta}$  and  $W^{1,p}$ ,  $p > 2$ . We perform first a calculation similar to that leading to the  $H_0^1$  estimate. To  $u_{\nu}$  we associate a constant  $c_{\nu}$  which is arbitrary except

$$(4.37) \quad |c_{\nu}| \leq \rho$$

and set now

$$F = \prod_{\nu=1}^N \exp \beta(\gamma_{\nu}(u_{\nu} - c_{\nu})).$$

Let also  $\psi$  be a function such that

$$(4.38) \quad \psi \geq 0, \psi \in C^1(\bar{\mathcal{O}}), \psi|_{\partial\mathcal{O}} = 0 \quad \text{if and only if} \\ \text{one of the constants } c_{\nu} \neq 0.$$

We test (4.1) with  $F\gamma_{\nu}\beta'(\gamma_{\nu}(u_{\nu} - c_{\nu}))\psi$ , which vanishes on the boundary of  $\mathcal{O}$ . We obtain instead of (4.33)

$$(4.39) \quad \sum_{\nu} \frac{1}{2} \int_{\mathcal{O}} \gamma_{\nu}^2 |Du_{\nu}|^2 e^{\gamma_{\nu}(u_{\nu} - c_{\nu})} F \psi dx + \frac{1}{2} \int_{\mathcal{O}} DF \cdot D\psi dx \leq \\ \leq \frac{1}{2} \int_{\mathcal{O}} F Q \cdot Q \psi dx + \int_{\mathcal{O}} \sum_{\nu} \gamma_{\nu} H_{\nu}^0(Du) F (e^{\gamma_{\nu}(u_{\nu} - c_{\nu})} - 1) \psi dx.$$

Introduce now

$$(4.40) \quad X = \prod_{v=1}^N (\exp \beta(\gamma_v(u_v - c_v)) + \exp \beta(-\gamma_v(u_v - c_v))),$$

$$X_v = X \frac{e^{\gamma_v(u_v - c_v)} \exp \beta(\gamma_v(u_v - c_v)) + e^{-\gamma_v(u_v - c_v)} \exp \beta(-\gamma_v(u_v - c_v))}{\exp \beta(\gamma_v(u_v - c_v)) + \exp \beta(-\gamma_v(u_v - c_v))},$$

$$\tilde{X}_v = X \frac{(e^{\gamma_v(u_v - c_v)} - 1) \exp \beta(\gamma_v(u_v - c_v)) - (e^{-\gamma_v(u_v - c_v)} - 1) \exp \beta(-\gamma_v(u_v - c_v))}{\exp \beta(\gamma_v(u_v - c_v)) + \exp \beta(-\gamma_v(u_v - c_v))}$$

and note that

$$(4.41) \quad DX = \sum_v \gamma_v \tilde{X}_v Du_v.$$

So writing (4.39) for all combinations of  $\gamma_v$  and  $-\gamma_v$ , and adding up yields

$$(4.42) \quad \frac{1}{2} \sum_v \int_{\mathcal{O}} \gamma_v^2 |Du_v|^2 X_v \psi dx + \frac{1}{2} \int_{\mathcal{O}} DX \cdot D\psi dx \leq \frac{1}{2} \int_{\mathcal{O}} X Q Q \psi dx +$$

$$+ \sum_v \int_{\mathcal{O}} \gamma_v H_v^0(Du) \tilde{X}_v \psi dx.$$

Picking the constants  $\gamma_v$  so that (4.35) holds we deduce that there exists two positive constants  $k_0, K_0$ , so that

$$(4.43) \quad k_0 \int_{\mathcal{O}} |Du|^2 \psi dx + \int_{\mathcal{O}} DX \cdot D\psi dx \leq K_0 \int_{\mathcal{O}} \psi dx.$$

We first apply (4.43) as follows: Let  $B_R(x_0)$ ,  $x_0 \in \mathbb{R}^n$ , be the ball of center  $x_0$  and radius  $R$ . Let  $\tau$  be a cut off function such that

$$\tau = \begin{cases} 1 & \text{on } B_1(0) \\ 0 & \text{outside } B_2(0) \end{cases}$$

and  $0 \leq \tau \leq 1$ ,  $\tau \in C^\infty$ . We denote

$$\tau_R(x) = \tau \left( \frac{x - x_0}{R} \right).$$

We define the constants  $c_\nu$  as follows:

$$(4.44) \quad c_\nu = c_\nu^R = \begin{cases} \frac{1}{|B_{2R}|} \int_{B_{2R}} u_\nu dx & \text{if } B_{2R} \subset \mathcal{O} \\ 0 & \text{if } B_{2R} \cap (\mathbb{R}^n - \mathcal{O}) \neq \emptyset, \end{cases}$$

and we take

$$(4.45) \quad \psi = \tau_R^2$$

so (4.38) is verified. We extend  $u$  by 0 outside  $\mathcal{O}$ , and we note that

$$|\tilde{X}_\nu| \leq C|u_\nu - c_\nu^R|,$$

$$|DX| \leq C|u - c^R| |Du|,$$

where  $c^R$  represents the vector  $c_\nu^R$ . Therefore we deduce from (4.43)

$$(4.46) \quad \int_{B_R} |Du|^2 dx \leq c \int_{B_{2R}} |Du| \frac{|u - c^R|}{R} dx + cR^n.$$

Such a property implies that

$$(4.47) \quad u_\nu \in W_0^{1,p}(\mathcal{O}), \quad 2 \leq p < 2 + \varepsilon.$$

It is a consequence of results of Gehring and Giaquinta-Modica. Indeed, from Hölder's inequality and Poincaré's inequality, we have

$$\begin{aligned} \int_{B_{2R}} |Du| \frac{|u - c^R|}{R} dx &\leq \frac{c}{R} \left( \int_{B_{2R}} |Du|^{\frac{2n}{n+1}} dx \right)^{\frac{n+1}{2n}} \left( \int_{B_{2R}} |u - c^R|^{\frac{2n}{n-1}} dx \right)^{\frac{n-1}{2n}} \\ &\leq \frac{c}{R} \left( \int_{B_{6R}} |Du|^{\frac{2n}{n+1}} dx \right)^{\frac{n+1}{n}}. \end{aligned}$$

Setting  $z = |Du|^{\frac{2n}{n+1}}$ , we have the inequality

$$(4.48) \quad \oint_{B_R} z^{\frac{n+1}{n}} dx \leq \left( \oint_{B_{6R}} z dx \right)^{\frac{n+1}{n}} + c,$$

where  $\oint_{B_R} = \frac{1}{R^n} \int_{B_R}$ .

This is the reverse Hölder's inequality, which implies Gehring's result, namely  $z^{\frac{n+1}{n}+\varepsilon}$  is integrable for some positive  $\varepsilon$ , hence (4.47), see [7], [8].

The obtaining of  $C^\delta$  is more delicate: The idea is to estimate the Morrey norm, that is to say to check that

$$(4.49) \quad \int_{B_R(x_0)} |Du|^2 dx \leq KR^{n-2+2\delta}, \quad \forall R, \forall x_0.$$

This implies  $C^\delta$ . Indeed one relies on Morrey's result

$$(4.50) \quad \sup_{\substack{x,y \\ x \neq y}} \frac{|u(x) - u(y)|}{|x - y|^\delta} \leq C \left( \frac{\sup_{x_0, R} \int_{B_R(x_0)} |Du|^2 dx}{R^{n-2+2\delta}} \right)^{1/2}.$$

To check (4.49) we shall prove the inequality

$$(4.51) \quad \int_{B_R} |Du|^2 |x - x_0|^{2-n} dx \leq C \int_{B_{\sigma R} - B_R} |Du|^2 |x - x_0|^{2-n} dx + CR^\beta,$$

where  $\sigma > 2$ ,  $\beta > 0$ . One then relies on the hole filling technique of Widman [13], to assert that (4.49) holds for some  $\delta$  such that  $2\delta < \beta$ . Indeed (4.51) implies

$$(4.52) \quad \int_{B_R} |Du|^2 |x - x_0|^{2-n} dx \leq \theta \int_{B_{\sigma R}} |Du|^2 |x - x_0|^{2-n} dx + CR^\beta$$

with  $\theta < 1$ , and setting

$$\varphi(R) = R^{-2\delta} \int_{B_R} |Du|^2 |x - x_0|^{2-n} dx$$

with  $2\delta < \beta$ ,  $\mu = \theta\sigma^{2\delta} < 1$ , we deduce

$$\varphi(R) \leq \mu\varphi(\sigma R) + C \quad \text{for } R < R_0$$

which implies  $\varphi(R) \leq C$ , provided  $\varphi(R_0) < \infty$ .

*Proof of (4.51).* We consider the Green function  $G = G^{x_0}$ , solution of

$$\begin{aligned} -\frac{1}{2}\Delta G^{x_0} &= \delta(x - x_0), & x_0 \in Q, \\ G|_{\partial Q} &= 0, \end{aligned}$$

where  $Q \supset \bar{\mathcal{O}}$ . We know that (see (4.16), (4.17))

$$(4.53) \quad G^{x_0} \in L^q(Q) \cap W_0^{1,n}(Q), \quad 1 \leq q < \frac{n}{n-2}, \quad 1 \leq n < \frac{n}{n-1}$$

and also

$$(4.54) \quad c_0|x - x_0|^{2-n} \leq G^{x_0} \leq c_1|x - x_0|^{2-n}$$

in a neighborhood of  $x_0$  strictly included in  $Q$ . So this estimate will be valid on  $\bar{Q}$ . We apply (4.43) with

$$(4.55) \quad \psi = G^{x_0} \tau_R^2$$

and

$$(4.56) \quad c_v = c_v^R = \begin{cases} \frac{1}{|B_{2R} - B_{R/2}|} \int_{B_{2R} - B_{R/2}} u_v dx & \text{if } B_{2R} \subset \mathcal{O} \\ 0 & \text{if } B_{2R} \cap (\mathbb{R}^n - \mathcal{O}) \neq \emptyset. \end{cases}$$

Consider the various terms in (4.43). We first have

$$(4.57) \quad k_0 \int_{\mathcal{O}} |Du|^2 G^{x_0} \tau_R^2 dx \geq c \int_{B_R} |Du|^2 |x - x_0|^{2-n} dx.$$

We next have

$$(4.58) \quad \int_{\mathcal{O}} G^{x_0} \tau_R^2 dx \leq CR^{\frac{n}{q}} = CR^\beta, \quad \beta < 2.$$

Next

$$D\psi = DG\tau_R^2 + 2G\tau_R D\tau_R.$$

Consider

$$I = \int_{\mathcal{O}} DXD\tau_R G\tau_R dx$$

and using

$$(4.59) \quad |dX| \leq C|u - c^R| |Du|,$$

we have

$$|I| \leq \int_{B_{2R} - B_R} |Du| \frac{|u - c^R|}{R} G dx \leq$$

$$\leq c \int_{B_{2R}-B_R} |Du|^2 |x - x_0|^{2-n} dx + c \int_{(B_{2R}-B_R) \cap \mathcal{O}} \frac{|u - c^R|^2}{R^2} |x - x_0|^{2-n} dx.$$

But

$$\begin{aligned} \int_{(B_{2R}-B_R) \cap \mathcal{O}} \frac{|u - c^R|^2}{R^2} |x - x_0|^{2-n} dx &\leq \frac{c}{R^n} \int_{(B_{2R}-B_R) \cap \mathcal{O}} |u - c^R|^2 dx \leq \\ &\leq \frac{c}{R^n} \int_{(B_{2R}-B_{R/2}) \cap \mathcal{O}} |u - c^R|^2 dx, \end{aligned}$$

and by Poincaré's inequality

$$\int_{(B_{2R}-B_{R/2}) \cap \mathcal{O}} |u - c^R|^2 \leq CR^2 \int_{B_{\sigma R}-B_{R/2}} |Du|^2 dx, \quad \sigma > 2,$$

hence collecting results, one has

$$(4.60) \quad |I| \leq C \int_{B_{\sigma R}-B_{R/2}} |Du|^2 |x - x_0|^{2-n} dx.$$

The other term

$$(4.61) \quad II = \int_{\mathcal{O}} DXDG\tau_R^2 dx,$$

which involves  $DG$ , is more complicated to estimate. We have to change  $X$  into  $X - 2^N$ :

$$II = \int_{\mathcal{O}} DG \cdot D((X - 2^N)\tau_R^2) dx - 2 \int_{\mathcal{O}} DGD\tau_R(X - 2^N)\tau_R dx.$$

Without loss of generality we can assume that  $B_{2R} \subset Q$ , hence using  $X \geq 2^N$ , we have from the definition of the Green function

$$II > -c \int_{(B_{2R}-B_R) \cap \mathcal{O}} |DG| \frac{|u - c^R|^2}{R} \tau_R dx,$$

where we have used the property

$$(4.62) \quad |X^N - 2^N| \leq C|u - c^R|^2.$$

We estimate  $II$  from below as follows:

$$II > -c \int_{(B_{2R}-B_R) \cap \mathcal{O}} G \frac{|u - c^R|^2}{R^2} dx - c \int_{(B_{2R}-B_R) \cap \mathcal{O}} G^{-1} |DG|^2 |u - c^R|^2 \tau_R^2 dx.$$

The first term in the right-hand side is estimated by the right-hand side of (4.60).

We need thus to estimate the term

$$III = \int_{(B_{2R}-B_R) \cap \mathcal{O}} G^{-1} |DG|^2 |u - c^R|^2 \tau_R^2 dx.$$

To estimate this quantity, we introduce a new cut off function satisfying

$$\xi = \begin{cases} 0 & \text{for } |x| \leq \frac{1}{2} \\ \tau & \text{for } |x| > 1, \end{cases}$$

and we set

$$\xi_R(x) = \xi\left(\frac{x - x_0}{R}\right).$$

Thus

$$\xi_R = \tau_R \text{ on } B_{2R} - B_R.$$

From the Green function equation we deduce, by testing with  $G^{-1}|u - c^R|^2 \xi_R^2$ , which vanishes in  $x_0$ , and on the boundary of  $\mathcal{O}$

$$(4.63) \quad \frac{1}{4} \int_{\mathcal{O}} |DG|^2 G^{-\frac{3}{2}} |u - c^R|^2 \xi_R^2 dx = \int_{\mathcal{O}} D(|u - c^R|^2 \xi_R^2) \cdot DGG^{-\frac{1}{2}} dx.$$

On the other hand

$$\begin{aligned} \int_{\mathcal{O}} \left(-\frac{1}{2} \Delta u_\nu\right) (u_\nu - c_\nu^R) G^{\frac{1}{2}} \xi_R^2 dx &= \frac{1}{2} \int_{\mathcal{O}} |Du_\nu|^2 G^{\frac{1}{2}} \xi_R^2 dx + \\ &+ \frac{1}{8} \int_{\mathcal{O}} D(\xi_R^2 |u - c^R|^2) DGG^{-\frac{1}{2}} dx + \\ &+ \int_{\mathcal{O}} Du_\nu D\xi_R \xi_R (u_\nu - c_\nu^R) G^{\frac{1}{2}} dx - \\ &- \frac{1}{4} \int_{\mathcal{O}} D\xi_R DG |u - c^R|^2 G^{-\frac{1}{2}} \xi_R dx, \end{aligned}$$

so

$$\frac{1}{8} \int_{\mathcal{O}} D(\xi_R^2 |u - c^R|^2) DGG^{-\frac{1}{2}} dx \leq \int_{\mathcal{O}} H_\nu (u_\nu - c_\nu^R) G^{\frac{1}{2}} \xi_R^2 dx -$$

$$- \int_{\mathcal{O}} Du_{\nu} D\xi_R \xi_R (u_{\nu} - c_{\nu}^R) G^{\frac{1}{2}} dx + \frac{1}{4} \int_{\mathcal{O}} D\xi_R DG |u - c^R|^2 G^{-\frac{1}{2}} \xi_R dx,$$

and from the quadratic growth of  $H_{\nu}$

$$\begin{aligned} \frac{1}{8} \int_{\mathcal{O}} D(\xi_R^2 |u - c^R|^2) DGG^{-\frac{1}{2}} dx &\leq CR^{n(1-\frac{1}{2q})} + CR^{\frac{2-n}{2}} \int_{B_{2R}-B_{R/2}} |Du|^2 dx + \\ &+ CR^{\frac{2-n}{2}} \int_{(B_{2R}-B_{R/2}) \cap \mathcal{O}} \frac{|u - c^R|^2}{R^2} dx + \frac{1}{4} \int_{\mathcal{O}} D\xi_R DG |u - c^R|^2 G^{-1/2} \xi_R dx. \end{aligned}$$

Furthermore

$$\begin{aligned} \int_{\mathcal{O}} D\xi_R DG |u - c^R|^2 G^{-1/2} \xi_R dx &\leq C\delta \int_{\mathcal{O}} |DG|^2 G^{-3/2} |u - c^R|^2 \xi_R^2 dx + \\ &+ \frac{c}{\delta} R^{\frac{2-n}{2}} \int_{(B_{2R}-B_{R/2}) \cap \mathcal{O}} \frac{|u - c^R|^2}{R^2} dx. \end{aligned}$$

Collecting results and choosing  $\delta$  sufficiently small, we have

$$\begin{aligned} \int_{\mathcal{O}} |DG|^2 G^{-3/2} |u - c^R|^2 \xi_R^2 dx &\leq CR^{n(1-\frac{1}{2q})} + \\ &+ CR^{\frac{2-n}{2}} \int_{(B_{2R}-B_{R/2}) \cap \mathcal{O}} \frac{|u - c^R|^2}{R^2} dx + CR^{\frac{2-n}{2}} \int_{B_{2R}-B_{R/2}} |Du|^2 dx, \end{aligned}$$

and from Poincaré's inequality it follows

$$\int_{\mathcal{O}} |DG|^2 G^{-3/2} |u - c^R|^2 \xi_R^2 dx \leq CR^{n(1-\frac{1}{2q})} + CR^{\frac{2-n}{2}} \int_{B_{\sigma R}-B_{R/2}} |Du|^2 dx.$$

Going back to the definition of  $III$  and recalling that  $\xi_R = \tau_R$  on  $B_{2R} - B_R$  we get

$$III \leq CR^{\frac{2-n}{2}} \int_{\mathcal{O}} G^{-\frac{3}{2}} |DG|^2 |u - c^R|^2 \xi_R^2 dx,$$

and from the previous estimate

$$\begin{aligned} III &\leq CR^{2-n} \int_{B_{\sigma R}-B_{R/2}} |Du|^2 dx + CR^{1+\frac{n}{2q'}} \leq \\ &\leq C \int_{B_{\sigma R}-B_{R/2}} |Du|^2 |x - x_0|^{2-n} dx + CR^{1+\frac{n}{2q'}}. \end{aligned}$$

Therefore we can state the following inequality:

$$III \geq - \int_{B_{\sigma R} - B_{R/2}} |Du|^2 |x - x_0|^{2-n} dx - CR^{1+\frac{n}{2q}},$$

and from (4.43) we immediately get (4.51) with  $\beta = \frac{n}{q}$ , since  $\frac{n}{q} < 1 + \frac{n}{2q}$ .

To apply the Hole filling technique it remains to verify

$$(4.64) \quad \int_{\mathcal{O}} |Du|^2 |x - x_0|^{2-n} dx < C.$$

For that we use again (4.43) with  $c_\nu = 0$  and  $\psi = G$ . Since

$$\int_{\mathcal{O}} DX \cdot DG dx > 0,$$

the result (4.65) is obvious.

#### 4.5. $W^{2,s}$ -estimates.

From the linear theory and  $W^{1,p}$ ,  $C^\delta$  estimates, for some  $p > 2$ ,  $\delta > 0$  we can derive  $W^{2,s}$ -estimates for any  $s$ . This is thanks to an interpolation result and a boot strap argument. Indeed, if  $u^\nu \in W^{1,p_0} \cap C^\delta$ ,  $p_0 > 2$ ,  $\delta > 0$ , then  $\Delta u^\nu \in L^{\frac{p_0}{2}}$ . Therefore  $u^\nu \in W^{2,\frac{p_0}{2}}$  from linear regularity theory. It follows from Miranda-Nirenberg's interpolation theorem, see [12], that

$$u^\nu \in W^{1,p_1}, \quad \text{with } \frac{1}{p_1} = \frac{1}{p_0} - \frac{\delta}{2n},$$

provided  $p_0 < \frac{2n}{\delta}$ , and thus  $p_1 > p_0$ . After a finite number of steps we get  $p_1 \geq \frac{2n}{\delta}$ , and it follows that

$$u^\nu \in W_0^{1,p}(\mathcal{O}), \quad p > 2n,$$

and from the linear theory again

$$u^\nu \in W^{2,s}(\mathcal{O}), \quad s > n.$$

From Sobolev's imbedding theorem,  $u^\nu \in W^{1,n}$ ,  $\forall n$ , and from the linear theory again  $u^\nu \in W^{2,s}$ ,  $\forall s$ .

4.6. *The case of a positive 0-order term.*

As a preliminary to problem (4.1) we consider the problem

$$(4.65) \quad \begin{aligned} -\frac{1}{2}\Delta u_\nu + \alpha u_\nu &= H_\nu(x, Du) \\ u_\nu|_{\partial\mathcal{O}} &= 0 \end{aligned}$$

with  $\alpha > 0$ . For such a problem we can weaken the assumptions (4.7), (4.8) and (4.9), (4.10) as follows:

$$(4.66) \quad \sum_\nu H_\nu(x, p) \leq -\lambda - \bar{\lambda} \left| \sum_\nu p_\nu \right|^2, \quad \bar{\lambda} \geq 0, \quad \lambda \geq 0.$$

There exists a matrix  $\Gamma$  which satisfies the maximum principle and

$$(4.67) \quad H_\nu^\Gamma(x, p) \leq \lambda_\nu + \lambda_\nu^0 |p_\nu|^2, \quad \lambda_\nu, \lambda_\nu^0 \geq 0,$$

$$(4.68) \quad \sum_\nu H_\nu(x, p) \leq \lambda + \bar{\lambda} \left| \sum_\nu p_\nu \right|^2, \quad \bar{\lambda} \geq 0, \quad \lambda \geq 0.$$

There exists a matrix  $\Gamma$  which satisfies the maximum principle and

$$(4.69) \quad H_\nu^\Gamma(x, p) \geq -\lambda_\nu - \lambda_\nu^0 |p_\nu|^2, \quad \lambda_\nu, \lambda_\nu^0 \geq 0.$$

**Theorem 4.2.** *We assume that the functions  $H_\nu(x, p)$  satisfy (4.2), (4.11), (4.12), (4.13) and one or the other of the two sets of assumptions (4.66), (4.67) or (4.68), (4.69). Then for  $\alpha > 0$  there exists a solution of (4.65) which is in  $W^{2,s}(\mathcal{O})$ ,  $\forall s$ , such that  $2 \leq s < \infty$ .*

If one considers the developments of Sections 4.2, 4.3, 4.4, 4.5, the only thing which fails is the treatment of the  $L^\infty$ -estimate. But to recover the  $L^\infty$ -estimate in the present framework is very easy since we can rely on maximum principle arguments. Indeed, assuming first (4.66), (4.67), then we have

$$-\frac{1}{2}\Delta \sum_\nu u_\nu + \alpha \left( \sum_\nu u_\nu \right) \geq -\lambda - \bar{\lambda} \left| D \sum_\nu u_\nu \right|^2,$$

and if  $\xi$  is a point of negative minimum of  $\sum_\nu u_\nu$ , necessarily  $D \sum_\nu u_\nu(\xi) = 0$ ,  $\Delta \sum_\nu u_\nu(\xi) \geq 0$ , hence

$$\sum_\nu u_\nu(\xi) \geq -\frac{\lambda}{\alpha}.$$

Therefore

$$(4.70) \quad \sum_{\nu} u_{\nu}(x) \geq -\frac{\lambda}{\alpha}.$$

Next considering

$$(4.71) \quad \tilde{u} = \Gamma u,$$

we get the system

$$-\frac{1}{2}\Delta\tilde{u}_{\nu} + \alpha\tilde{u}_{\nu} = H^{\Gamma}(x, D\tilde{u}),$$

hence from the assumption (4.67), it follows

$$-\frac{1}{2}\Delta\tilde{u}_{\nu} + \alpha\tilde{u}_{\nu} \leq \lambda_{\nu} + \lambda_{\nu}^0 |D\tilde{u}_{\nu}|^2,$$

and if  $\xi_{\nu}$  is a point of positive maximum, necessarily

$$\tilde{u}_{\nu}(\xi_{\nu}) \leq \frac{\lambda_{\nu}}{\alpha}.$$

Therefore

$$(4.72) \quad \tilde{u}_{\nu}(x) \leq \frac{\lambda_{\nu}}{\alpha},$$

and since  $\Gamma$  satisfies the maximum principle, we get

$$(4.73) \quad u_{\nu}(x) \leq \frac{1}{\alpha} \sum_{\mu} (\Gamma^{-1})_{\nu\mu} \lambda_{\nu},$$

which combined with (4.70) yields the result.

The case of the assumptions (4.68), (4.69) is treated in a similar way.

Once we know  $L^{\infty}$ -estimates on  $\alpha u_{\nu}$ , then this term can be incorporated in the Lagrangian and the developments of Sections 4.3, 4.4, 4.5 can be made. Of course all the estimates on the functions  $u_{\nu}$  depend on  $\alpha$ .

*Proof of Theorem 4.2.* One considers an approximation as follows:

$$(4.74) \quad \begin{aligned} -\frac{1}{2}\Delta u_{\nu} + \alpha u_{\nu} &= \frac{H_{\nu}(x, Du)}{1 + \varepsilon |H(x, Du)|} = H_{\nu}^{\varepsilon}(x, Du) \\ u_{\nu}|_{\partial\mathcal{O}} &= 0, \end{aligned}$$

where  $H(x, p)$  represents the vector  $H_\nu(x, p)$ . Clearly the right-hand side is bounded in  $L^\infty$  by a constant depending on  $\varepsilon$ .

To show that (4.74) has a solution in  $W^{2,s}(\mathcal{O}) \cap W_0^{1,s}(\mathcal{O})$ ,  $\forall 2 \leq s < \infty$ , one relies on Schauder's fixed point Theorem. Indeed consider the set, for  $s$  arbitrary

$$(4.75) \quad K_\varepsilon = \left\{ z \in (W_0^{1,s}(\mathcal{O}))^N \mid \|z\|_{(W^{2,s})^N} \leq C \right\},$$

which is compact in  $(W_0^{1,s}(\mathcal{O}))^N$ . Consider next the map from  $(W_0^{1,s})^N$  into itself,  $T^\varepsilon \zeta = z$ , by solving

$$\begin{aligned} -\frac{1}{2} \Delta z_\nu + \alpha z_\nu &= H_\nu^\varepsilon(x, D\xi) \\ z_\nu|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

By choosing conveniently the constant  $C$  in the definition of  $K_\varepsilon$ , one can check that  $T^\varepsilon$  maps  $K_\varepsilon$  into itself. Moreover, from (4.2),  $T^\varepsilon$  is continuous. Hence the fixed point property applies. Now it is easy to check that  $H^\varepsilon$  satisfies all the assumptions of  $H$ , with the same constants, hence independent of  $\varepsilon$ . Hence the solution  $u^\varepsilon$  of (4.74) remains bounded in  $(W^{2,s}(\mathcal{O}))^N$  norm, independently of  $\varepsilon$ . Hence letting  $\varepsilon$  tend to 0, one obtains a solution of (4.65).  $\square$

*Proof of Theorem 4.1.* We can proceed on the solution  $u^\alpha$  of (4.65) in  $W^{2,s}$  which has been obtained with the development of Sections 4.2, 4.3, 4.4, 4.5. Thanks to the assumptions of Theorem 4.1 we can obtain estimates in  $W^{2,s}$ , which are independent of  $\alpha$ . We can then let  $\alpha$  tend to 0 to complete the proof.  $\square$

## 5. Hamiltonians arising from games.

### 5.1. Set up: case (4.7), (4.8).

We define here the Hamiltonians  $H_\nu(x, p)$  as follows:

$$(5.1) \quad H_\nu(x, p) = f_\nu(x) + g \cdot p_\nu + L_\nu(p) + \frac{\delta}{2} |p_\nu|^2,$$

where  $L_\nu(p)$  has been defined by (3.8) and  $f_\nu$  and  $g$  are the functions which arise in (2.10), (2.16). We first check (4.7), (4.8) with  $\Gamma = I$ . Using (3.53), (3.70) and formula (5.1), we obtain (4.8) with

$$(5.2) \quad \begin{aligned} \lambda_\nu^0 &= \frac{1-2\theta}{2\theta^2} + \frac{\delta}{2} + \frac{\varepsilon}{2}, \\ \lambda_\nu &= \|f_\nu\| + \frac{1}{2\varepsilon} \|g\|^2. \end{aligned}$$

Using (3.55) we have

$$\sum_{\nu} H_{\nu}(x, p) \geq -\left\| \sum_{\nu} f_{\nu} \right\| - \frac{N}{2\varepsilon} \|g\|^2 - \frac{\varepsilon}{2} |p|^2 + \frac{F_{\delta}(\theta) |p|^2}{(1-\theta)^2(1+(N-1)\theta)^2},$$

we obtain (4.7) with

$$(5.3) \quad \lambda = \left\| \sum_{\nu} f_{\nu} \right\| + \frac{N}{2\varepsilon} \|g\|^2$$

provided  $\theta$  belongs to the validity intervals defined in (3.70). If the product  $\lambda_{\nu} \lambda_{\nu}^0$  satisfies the condition (4.22), then the properties (4.7), (4.8) are satisfied.

Recalling that  $F_{\delta}(\theta) \geq F(\theta)$ , we may pick  $\theta < \theta'$  or  $\theta'' < \theta < \bar{\theta}$ , and we get a condition of smallness on  $\delta$  (note that  $\theta < 0$ ), from (4.22).

Let us verify (4.11), (4.12), (4.13). We define the matrix  $\Gamma$  as follows:

$$\begin{aligned} \Gamma_{\nu\mu} &= \delta_{\nu\mu} \text{ if } \nu = 1, \dots, N, \mu = 1, \dots, N-1, \\ \Gamma_{\nu N} &= -1 \text{ if } \nu = 1, \dots, N-1, \\ \Gamma_{NN} &= 1, \end{aligned}$$

hence setting  $\tilde{p} = \Gamma p$ , we have

$$H_{\nu}^{\Gamma}(x, \tilde{p}) = H_{\nu}(x, p) - H_N(x, p), \quad \forall \nu < N,$$

$$H_N^{\Gamma}(x, \tilde{p}) = H_N(x, p).$$

Using (3.12) it follows, after easy computations,

$$H_{\nu}^{\Gamma}(x, \tilde{p}) = Q(\tilde{p}) \tilde{p}_{\nu} + H_{\nu}^0(x, \tilde{p}),$$

with

$$Q(\tilde{p}) = \frac{2\theta - 1}{(1-\theta)^2(1+(N-1)\theta)} \sum_{\mu} \tilde{p}_{\mu} + \left( \frac{1-2\theta}{(1-\theta)^2} + \delta + N - 1 \right) p_N,$$

$$H_{\nu}^0(x, \tilde{p}) = f_{\nu} - f_N + g \cdot \tilde{p}_{\nu} + \frac{1}{2} \left( \delta + \frac{1-2\theta}{(1-\theta)^2} \right) |\tilde{p}_{\nu}|^2, \nu < N,$$

$$H_N^{\Gamma}(x, \tilde{p}) = H_N(x, p) - Q(\tilde{p}) \tilde{p}_N$$

and the assumptions (4.11), (4.12), (4.13) are easily verified.

5.2. *Set up: Case (4.9), (4.10).*

We are going to check satisfying (4.9), (4.10) with the following  $\Gamma$ :

$$(5.4) \quad \Gamma_{\nu\nu} = (N-1)\theta, \quad \Gamma_{\nu\mu} = -1 \quad \text{if } \mu \neq \nu.$$

This matrix satisfies the maximum principle, provided  $\theta > 1$ . Indeed its inverse is

$$\begin{aligned} (\Gamma^{-1})_{\nu\nu} &= \frac{(N-1)\theta - (N-2)}{(N-1)(\theta-1)((N-1)\theta+1)}, \\ (\Gamma^{-1})_{\nu\mu} &= \frac{1}{(N-1)(\theta-1)((N-1)\theta+1)}, \quad \mu \neq \nu, \end{aligned}$$

which are positive, under the assumption on  $\theta$ . This guarantees the maximum principle. We set

$$\tilde{p} = \Gamma p,$$

and we have (see (3.45), (3.70))

$$M_v^\Gamma(\tilde{p}) = \tilde{M}_v(p).$$

According to formula (3.79) and recalling (3.44), we get

$$(5.5) \quad M_v^\Gamma(\tilde{p}) \geq -k_0 |\tilde{p}_v|^2$$

with

$$(5.6) \quad k_0 = \frac{1}{2(1-\theta)^2(1+(N-1)\theta)^2} \left\{ \frac{(1-\theta)^2(1-\delta\theta(N-1))^2}{(N-1)\theta(1-\delta(\theta-1))} + \right. \\ \left. + (N-1)\theta(2\theta-1) \frac{\theta-1}{N-1} - \delta \left( \theta(\theta-1)(\theta(N-1) - N+3) + \frac{1}{N-1} \right) \right\}^+$$

provided we assume

$$(5.7) \quad \theta - \frac{1}{2} - \frac{\delta}{2}(\theta-1)^2 > 0$$

$$(5.8) \quad 1 - \delta(\theta-1) > 0.$$

Next,

$$H_v^\Gamma(x, \tilde{p}) = (N-1)\theta f_v(x) - \sum_{\mu \neq v} f_\mu(x) + g \cdot \tilde{p}_v + M_v^\Gamma(\tilde{p}) \geq$$

$$\geq -\lambda_\nu - \lambda_\nu^0 |\tilde{p}_\nu|^2$$

with

$$(5.9) \quad \begin{aligned} \lambda_\nu &= \|(N-1)\theta f_\nu - \sum_{\mu \neq \nu} f_\mu\| + \frac{1}{2\varepsilon} \|g\|^2 \\ \lambda_\nu^0 &= k_0 + \frac{\varepsilon}{2}, \end{aligned}$$

and (4.10) is satisfied, provided  $\lambda_\nu \lambda_\nu^0$  verifies (4.22).

Next we have

$$\sum_\nu H_\nu(x, p) \leq \left\| \sum_\nu f_\nu \right\| + \frac{N}{2\varepsilon} \|g\|^2 + \frac{\varepsilon}{2} |p|^2 + \frac{\hat{F}_\delta(\theta) |p|^2}{(1-\theta)^2 (1+(N-1)\theta)^2},$$

and we obtain (4.9) provided the conditions of Lemma 3.3 are fulfilled, namely  $\theta'_0 < \bar{\theta}'_\delta$  and  $\theta \in (\theta''_{1\delta}, \bar{\theta}'_\delta)$ . Since  $\theta > 1$ , and thanks to (3.66), this reduces to  $\bar{\theta}'_\delta > 1$ , and  $\theta \in (1, \bar{\theta}'_\delta)$ . Considering (3.61), this means

$$(5.10) \quad \delta < \frac{1 + 2N(N-1)}{N^2},$$

$$(5.11) \quad 1 < \theta < \frac{1}{\delta} \left( 1 - \frac{\delta}{N-1} + \sqrt{\frac{1+\delta}{(N-1)^2}} \right).$$

Summing up we can assert the

**Proposition 5.1.** *For the Hamiltonians (5.1), the assumptions (4.11), (4.12), (4.13) are satisfied. The conditions (4.7), (4.8) are verified with  $\lambda_\nu^0, \lambda_\nu$  given by (5.2).  $\lambda$  given by (5.3) with  $\Gamma = I$ , provided  $\theta$  belongs to the validity intervals defined in (3.70) and  $\lambda_\nu \lambda_\nu^0$  verifies the condition (4.22). On the other hand, the conditions (4.9), (4.10) are satisfied with  $\lambda_\nu^0, \lambda_\nu$  given by (5.9),  $\lambda$  given by (5.3), with  $\Gamma$  defined by (5.4), provided  $\theta > 1$  and  $\delta$  verify (5.7), (5.8), (5.10), (5.11),  $\lambda_\nu \lambda_\nu^0$  verifies the condition (4.22).*

## 6. Solution of the stochastic game problem.

### 6.1. Bellman system.

We relate to problem (2.17) the system of Bellman equations

$$(6.1) \quad \begin{aligned} -\frac{1}{2}\Delta u_v &= f_v + g \cdot Du_v + L_v(Du) + \frac{\delta}{2}|Du_v|^2 \\ u_v|_{\partial\mathcal{O}} &= 0, \end{aligned}$$

and we assume that all conditions of Proposition 5.1 are satisfied. Therefore, according to Theorem 4.1, there exists a solution in  $(W^{2,s}(\mathcal{O}) \cap W_0^{1,s}(\mathcal{O}))^N$ ,  $\forall 1 \leq s < \infty$ . We define the feedbacks

$$(6.2) \quad \hat{v}_v(x) = v_v(Du(x)),$$

where  $v_v(p)$  are given by (3.6). These functions are bounded and continuous. To such a feedback we associate the stochastic processes

$$(6.3) \quad \hat{v}_v(t) = \hat{v}_v(x(t)),$$

where  $x(t)$  is the process defined by (2.4). Our objective is to check that such a vector process  $\hat{v}(t)$  is the Nash point of the functionals  $J_v(x, v(\cdot))$  defined by (2.16), in the sense of (2.17). We state then

**Theorem 6.1.** *We assume all the conditions of Proposition 5.1, so that there exists a solution of the system (6.1) in the space  $(W^{2,s}(\mathcal{O}) \cap W_0^{1,s}(\mathcal{O}))^N$ . Then the control defined by (6.3), corresponding to the feedback defined by (6.2) is a Nash point of the functionals  $J_v(x, v(\cdot))$  defined by (2.16) in the sense of (2.17). Moreover one has*

$$(6.4) \quad u_v(x) = J_v(x, \hat{v}(\cdot)).$$

### 6.2. Proof of Theorem 6.1.

Note that from the Definition (6.2) we have

$$(6.5) \quad \begin{aligned} L_v(Du) &= \frac{1}{2}|\hat{v}_v(Du)|^2 + \theta \hat{v}_v(Du) \cdot \bar{\hat{v}}_v(Du) \leq \\ &\leq \frac{1}{2}|v_v|^2 + \theta v_v \cdot \bar{\hat{v}}_v(Du), \quad \forall x, \forall v_v. \end{aligned}$$

Applying this inequality to  $x = x(t)$ , yields, from (6.3)

$$(6.6) \quad \begin{aligned} L_v(Du(x(t))) &= \frac{1}{2}|\hat{v}_v(t)|^2 + \theta \hat{v}_v(t) \cdot \bar{v}_v(t) \leq \\ &\leq \frac{1}{2}|v_v(t)|^2 + \theta v_v(t) \cdot \bar{v}_v(t), \end{aligned}$$

for any control  $v_v$ .

Consider the probability  $P_{x,\hat{v}}$  defined by (2.8), where  $\hat{v}(\cdot)$  is the process defined by (6.3). Note that for the system  $(\Omega, \mathcal{A}, \mathcal{F}^t, P_{x,\hat{v}}, w_{x,\hat{v}})$  we have (see (2.10))

$$(6.7) \quad dx = \left( g(x(t)) + \sum_{\mu} \hat{v}_{\mu}(t) \right) dt + dw_{x,\hat{v}}(t), \quad x(0) = x.$$

From Ito's formula we have

$$\begin{aligned} du_v(x(t)) &= \left( Du_v(x(t)) \cdot (g(x(t)) + \sum_{\mu} \hat{v}_{\mu}(t)) + \right. \\ &\quad \left. + \frac{1}{2} \Delta u_v(x(t)) \right) dt + Du_v(x(t)) dw_{x,\hat{v}}(t) \end{aligned}$$

and from the Bellman equation (6.1) we deduce

$$(6.8) \quad \begin{aligned} du_v(x(t)) &= -f_v(x(t)) - \frac{1}{2}|\hat{v}_v(t)|^2 - \theta \hat{v}_v(t) \cdot \bar{v}_v(t) - \\ &\quad - \frac{\delta}{2} |Du_v(x(t))|^2 + Du_v(x(t)) \cdot dw_{x,\hat{v}}(t). \end{aligned}$$

Integrating between 0 and  $\tau_x$  yields

$$(6.9) \quad \begin{aligned} u_v(x) &= \int_0^{\tau_x} \left[ f_v(x(t)) + \frac{1}{2}|\hat{v}_v(t)|^2 + \theta \hat{v}_v(t) \cdot \bar{v}_v(t) \right] dt - \\ &\quad - \int_0^{\tau_x} Du_v(x(t)) dw_{x,\hat{v}}(t) + \frac{\delta}{2} \int_0^{\tau_x} |Du_v(x(t))|^2 dt \end{aligned}$$

hence

$$(6.10) \quad \exp \delta \int_0^{\tau_x} \left[ f_v(x(t)) + \frac{1}{2}|\hat{v}_v(t)|^2 + \theta \hat{v}_v(t) \cdot \bar{v}_v(t) \right] dt =$$

$$= \exp \delta u_\nu(x) \exp \left( \int_0^{\tau_x} \delta Du_\nu(x(t)) dw_{x,\hat{v}}(t) - \frac{1}{2} \int_0^{\tau_x} |\delta Du_\nu(x(t))|^2 dt \right).$$

Since

$$\exp \left( \int_0^t \delta Du_\nu(x(s)) dw_{x,\hat{v}}(s) - \frac{1}{2} \int_0^t |\delta Du_\nu(x(s))|^2 ds \right)$$

is an  $\mathcal{F}^t$ ,  $P_{x,\hat{v}}$  martingale, and  $\tau_x$  is a stopping time, we deduce the formula

$$(6.11) \quad \exp \delta u_\nu(x) = E_{x,\hat{v}} \exp \delta \int_0^{\tau_x} \left[ f_\nu(x(t)) + \frac{1}{2} |\hat{v}_\nu(t)|^2 + \theta \hat{v}_\nu(t) \cdot \bar{v}(t) \right] dt$$

hence (6.4) is demonstrated.

Next considering an arbitrary control  $v(\cdot)$ , we manufacture the control  $(v_\nu(\cdot), \hat{v}^\nu(\cdot))$ , in which we take for all components  $\mu \neq \nu$  the control  $\hat{v}_\mu(\cdot)$  defined by (6.3), and for the component  $\nu$  the control  $v_\nu(\cdot)$ . Performing similar calculations as above and taking account this time of the inequality (6.6) we can check that

$$u_\nu(x) \leq J_\nu(x, v_\nu, \hat{v}_\nu),$$

which establishes the inequality (2.17).

The proof has been completed.  $\square$

## Appendix 1.

*Discussion on the smallness of  $\lambda_\nu \lambda_\nu^0$ .*

First we argue that a smallness condition on  $\lambda_\nu \lambda_\nu^0$  (see (4.8) and (4.10)) cannot be avoided. Consider indeed the case of  $N = 1$ , and in dimension one the equation

$$\begin{aligned} -\frac{1}{2} u'' &= \lambda + \lambda^0 u'^2 \\ u(0) &= u(1) = 1. \end{aligned}$$

For  $\lambda^0 \leq 0$  it is easy to check that there exists a unique bounded solution. For  $\lambda^0 > 0$  the unique possible solution is

$$u(x) = \frac{1}{2\lambda^0} \log \left| \frac{\cos \sqrt{\lambda^0 \lambda} (2x - 1)}{\cos \sqrt{\lambda^0 \lambda}} \right|,$$

which is bounded if and only if  $\lambda^0 \lambda < \frac{\pi^2}{4}$ .

Let us compare with the limitation obtained in (4.22). In the present example, the Green function  $G^\xi(x)$  is given by

$$G^\xi(x) = \begin{cases} 2(1-\xi)x & \text{if } 0 \leq x \leq \xi \\ 2\xi(1-x) & \text{if } \xi \leq x \leq 1 \end{cases}$$

and

$$\int_0^1 G^\xi(x) dx = \xi(1-\xi) \leq \frac{1}{4}.$$

Therefore, condition (4.22) means here  $\lambda^0\lambda < 1$ . So we do not get the optimum limitation by this method, as can be expected.

So the issue of the improvement of the limitation on  $\lambda^0\lambda$  is an interesting question. We shall check in the following result that an improvement can arise from the presence of an adequate drift  $g$ . This is reminiscent of what occurs in the finite horizon problem (see [6]).

*A variant of Theorem 4.1.*

We consider here the problem

$$(1) \quad \begin{aligned} -\frac{1}{2}\Delta u_\nu - g \cdot Du_\nu &= H_\nu(x, Du) \\ u_\nu|_{\partial\mathcal{O}} &= 0, \end{aligned}$$

which, compared to (4.1), has a linear first order term  $-g \cdot Du_\nu$ . Of course, the usual treatment would be to incorporate it in the Hamiltonian  $H_\nu$ , but as far as condition (4.8) is concerned, this implies a deterioration of the smallness condition on  $\lambda_\nu\lambda_\nu^0$ . In fact, we shall see here that this term can relax to a large extent the limitation on  $\lambda_\nu\lambda_\nu^0$ , provided  $\operatorname{div} g > 0$ .

We proceed as follows: Considering the function  $E_\nu$  in (4.20), we can check that

$$(2) \quad -\frac{1}{2}\Delta E - gDE_\nu \leq 2\lambda_\nu\lambda_\nu^0 E_\nu.$$

Since everything relates to the  $\nu$  equation, we shall drop the symbol  $\nu$  in the sequel. So, also

$$(3) \quad \begin{aligned} -\frac{1}{2}\Delta(E-1) - g \cdot D(E-1) &\leq 2\lambda\lambda^0(E-1) + 2\lambda\lambda^0 \\ (E-1)|_{\partial\mathcal{O}} &= 0. \end{aligned}$$

We first check that under some smallness conditions we can obtain an estimate on  $E - 1$  in  $L^2(\mathcal{O})$ . Indeed, testing (3) with  $(E - 1)^+$  yields

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{O}} |D(E - 1)^+|^2 dx + \int_{\mathcal{O}} \frac{\operatorname{div} g}{2} [(E - 1)^+]^2 dx &\leq \\ &\leq 2\lambda\lambda^0 \int_{\mathcal{O}} [(E - 1)^+]^2 dx + 2\lambda\lambda^0 \int_{\mathcal{O}} (E - 1)^+ dx. \end{aligned}$$

From Poincaré's inequality we get

$$\int_{\mathcal{O}} (k_0 + \operatorname{div} g) [(E - 1)^+]^2 dx \leq 4\lambda\lambda^0 \int_{\mathcal{O}} [(E - 1)^+]^2 dx + 4\lambda\lambda^0 \int_{\mathcal{O}} (E - 1)^+ dx,$$

and if the smallness condition

$$(4) \quad 4\lambda\lambda^0 < k_0 + \inf \operatorname{div} g$$

is satisfied, then clearly

$$(5) \quad \int_{\mathcal{O}} (E - 1)^2 dx \leq |\mathcal{O}| + \int_{\mathcal{O}} [(E - 1)^+]^2 dx \leq c,$$

hence also

$$(6) \quad \int_{\mathcal{O}} E^2 dx \leq c.$$

From that knowledge, we are going to check that  $E$  is bounded in  $L^\infty$ , without using any more any smallness condition. We test (3) with  $EG^\xi$ , using again the Green function (4.15) (although the Green function related to the operator  $-\frac{1}{2}\Delta - g \cdot D$  is also possible). We obtain

$$\begin{aligned} (7) \quad \frac{1}{2} \int_{\mathcal{O}} |DE|^2 G^\xi dx + \frac{1}{4} \int_{\mathcal{O}} D(E^2 - 1) DG^\xi dx &\leq \\ &\leq \int_{\mathcal{O}} E^2 G^\xi \left( 2\lambda\lambda^0 - \frac{1}{2} \operatorname{div} g \right) dx - \\ &- \int_{\mathcal{O}} \frac{1}{2} E^2 g \cdot \operatorname{grad} G^\xi dx + \frac{1}{2} \int_{\mathcal{O}} (G^\xi \operatorname{div} g + g \cdot \operatorname{grad} G^\xi) dx, \end{aligned}$$

and from the definition of the Green function we deduce

$$(8) \quad E^2(\xi) \leq 1 + \int_{\mathcal{O}} E^2 G^\xi (4\lambda\lambda^0 - \operatorname{div} g) dx - \int_{\mathcal{O}} E^2 \operatorname{grad} G^\xi dx + \\ + \int_{\mathcal{O}} (G^\xi \operatorname{div} g + g \cdot \operatorname{grad} G^\xi) dx .$$

We now make use of (6). Consider the set  $\{x : E(x) > L\}$ , where  $L$  is large  $> 1$ . We split the integrals on the right-hand side of (8) into the integral on this set and on its complement. Assuming  $\xi$  is chosen to be the maximum of  $E$ , supposed to be larger than 1 (otherwise the  $L^\infty$  bound is obvious), we can then deduce from (8) the inequality

$$(9) \quad \|E^2\|_{L^\infty} \leq 1 + L^2(4\lambda\lambda^0 + \|\operatorname{div} g\|) \int_{\mathcal{O}} G^\xi dx + \\ + L^2\|g\| \int_{\mathcal{O}} |DG^\xi| dx + \|E^2\|_\infty(4\lambda\lambda^0 + \|\operatorname{div} g\|) \int_{\{E>L\}} G^\xi dx + \\ + \|E^2\|_\infty \|g\| \int_{\{E>L\}} |DG^\xi| dx + C .$$

Now from (6) we have

$$(10) \quad \operatorname{Meas} \{E > L\} \leq \frac{C}{L^2} ,$$

and from the estimates (4.16), (4.17) we can assert, thanks to Hölder's inequality,

$$(11) \quad \int_{\{E>L\}} G^\xi dx \leq C \|G^\xi\|_{L^q} \frac{1}{L^{2q'}} ,$$

$$(12) \quad \int_{\{E>L\}} |DG^\xi| dx \leq C \|G^\xi\|_{L^{r'}} \frac{1}{L^{2r'}} .$$

By picking  $L$  sufficiently large, the coefficient in front of  $\|E^2\|_\infty$  in the right-hand side of (9) can be made as small as we wish, hence strictly smaller than 1. Then (9) yields an estimate on the  $L^\infty$  norm of  $E$ .

The rest of the proof of Theorem 4.1 is unchanged.

Considering the limitation (4), it can be very good if  $\inf \operatorname{div} g$  is very large. However this estimate, which can be also used when  $g = 0$ , is not very good in that case. For example in our one dimensional example, the Poincaré constant  $k_0 = 1$ , hence  $\lambda\lambda^0 < \frac{1}{4}$ , which is much worse than 1 obtained from (4.22).

**Appendix 2.**

*Global smallness condition.*

If we consider (4.7) and (4.8) with  $\Gamma = I$ , we get the property

$$(1) \quad -\lambda - \sum_{\mu \neq v} \lambda_{\mu} - \sum_{\mu \neq v} \lambda_{\mu}^0 |p_{\mu}|^2 \leq H_v(x, p) \leq \lambda_v + \lambda_v^0 |p_v|^2,$$

and  $\lambda_v, \lambda_v^0$  not too large. This is reminiscent, although *not equivalent* to a global smallness assumption on  $k, K$ , where

$$(2) \quad |H(x, p)| \leq k|p|^2 + K.$$

In that case things simplify greatly (see [9]).

For the sake of completeness we sketch the main arguments in the case of a global small assumption. First to obtain  $L^{\infty}$  estimates, we test the equation

$$(3) \quad -\frac{1}{2} \Delta u_v = H_v(x, Du)$$

with  $G^{\xi} u_v$ , which yields

$$\int_{\mathcal{O}} D|u|^2 DG^{\xi} dx + \frac{1}{2} \int_{\mathcal{O}} G^{\xi} |Du|^2 dx = \int_{\mathcal{O}} G^{\xi} |u| |H(x, Du)| dx$$

hence if  $\xi$  is a point where  $|u|$  reaches its maximum, we have

$$\|u\|_{\infty}^2 + \frac{1}{2} \int_{\mathcal{O}} G^{\xi} |Du|^2 dx \leq \|u\|_{\infty} \int_{\mathcal{O}} G^{\xi} (K + k|Du|^2) dx$$

thus if we have

$$(4) \quad 2k\|u\|_{\infty} < 1,$$

then it follows

$$\|u_{\infty}\| < K \int_{\mathcal{O}} G^{\xi} dx,$$

so it is sufficient to assume

$$(5) \quad 2kK\|G\|_{L^1} < 1.$$

The  $H_0^1$  estimate follows, since testing (3) with  $u_\nu$  yields

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{O}} |Du|^2 dx &\leq \|u\|_\infty \int_{\mathcal{O}} |H| dx \leq \\ &\leq \|u\|_\infty \left( \int_{\mathcal{O}} k|Du|^2 dx + K \text{Meas } \mathcal{O} \right), \end{aligned}$$

and we make use of (4) to derive the  $H_0^1$  estimate.

To obtain the  $C^\delta$  and  $W^{1,p}$  estimate,  $2 \leq p < 2 + \varepsilon$ , we test with  $(u_\nu - c_\nu^R)\tau_R^2$ , where  $\tau_R, c_\nu^R$  have been defined in (4.44), (4.45). We obtain

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{O}} |Du|^2 \tau_R^2 dx + \int_{\mathcal{O}} (u_\nu - c_\nu^R) Du_\nu D\tau_R \tau_R dx &\leq \\ \leq \|u - c^R\|_\infty \int_{\mathcal{O}} (k|Du|^2 + K)\tau_R^2 dx &\leq 2\|u\|_\infty \int_{\mathcal{O}} (k|Du|^2 + K)\tau_R^2 dx, \end{aligned}$$

so if we assume a more stringent assumption that (5), namely

$$(6) \quad 4kK\|G\|_{L^1} < 1,$$

which implies

$$4k\|u\|_\infty < 1,$$

then we get

$$(7) \quad c_0 \int_{B_R} |Du|^2 dx \leq C \int_{B_{2R}} |Du| \frac{|u - c^R|}{R} dx + CR^n,$$

which is the condition (4.46).

Similarly we can obtain (4.51) by testing with  $(u_\nu - c_\nu^R)G^{x_0}\tau_R^2$ , where  $G^{x_0}$  has been defined in (4.53). We get this time

$$\begin{aligned} \frac{1}{2} \int_{\mathcal{O}} |Du|^2 G^{x_0} \tau_R^2 dx + \int_{\mathcal{O}} (u_\nu - c_\nu^R) Du_\nu D\tau_R \tau_R G^{x_0} dx &\leq \\ \leq 2\|u\|_\infty \int_{\mathcal{O}} (k|Du|^2 + K) G^{x_0} \tau_R^2 dx, \end{aligned}$$

and by virtue of (6),

$$c_0 \int_{\mathcal{O}} |Du|^2 G^{x_0} \tau_R^2 dx \leq \int_{\mathcal{O}} |u - c^R| |Du| |D\tau_R| \tau_R G^{x_0} dx + C \int_{\mathcal{O}} G^{x_0} \tau_R^2 dx.$$

Then making use of the properties of the Green function (see (4.54)), using Hölder's inequality, then Poincaré's inequality, we derive (4.51) easily.

It is also possible to get rid of the more stringent assumption (6) and to assume only (5), see [9].

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