

BOUNDARY REGULARITY RESULTS FOR NON-VARIATIONAL BASIC ELLIPTIC SYSTEMS

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Dedicated to Professor Sergio Campanato on his 70th birthday

Let $u \in H^2(B^+(1), \mathbb{R}^N)$ (N integer ≥ 1) be a solution to the following problem

$$\begin{cases} u = g & \text{on } \Gamma, \\ a(H(u)) = 0 & \text{in } B^+(1), \end{cases}$$

where $a(\xi)$ is a vector of \mathbb{R}^N , continuous onto \mathbb{R}^{n^2N} , $\Gamma = \{x \in \mathbb{R}^n : \|x\| < 1, x_n = 0\}$, and $B^+(1) = \{x \in \mathbb{R}^n : \|x\| < 1, x_n > 0\}$. We prove that, if $a(\xi)$ satisfies the conditions $a(0) = 0$ and (C) (see Section 1 below) while $g \in H^3(B^+(1), \mathbb{R}^N)$, then $u \in H^3(B^+(\sigma), \mathbb{R}^N)$, for all $\sigma \in (0, 1)$. Exploiting it we next deduce the Hölder-continuity of the vectors Du and u in $B^+(\sigma)$, provided $2 \leq n < 4$ or $2 \leq n < 6$, respectively. These results are basic tools for studying the Hölder-continuity in $\bar{\Omega}$ of the solutions to the Dirichlet problem

$$\begin{cases} u \in H^2(\Omega, \mathbb{R}^N), \\ u = g & \text{on } \partial\Omega, \\ a(H(u)) = 0 & \text{in } \Omega. \end{cases}$$

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1. Introduction.

Let Ω be a bounded open set in \mathbb{R}^n , $n \geq 2$, with generic point $x = (x_1, x_2, \dots, x_n)$. If $u(x)$ is a vector $\Omega \rightarrow \mathbb{R}^N$, N integer ≥ 1 , we write

$$D_i u = \frac{\partial u}{\partial x_i}, \quad Du = (D_1 u, D_2 u, \dots, D_n u),$$

$$H(u) = \{D_i D_j u\} = \{D_{ij} u\}, \quad i, j = 1, 2, \dots, n;$$

obviously, Du and $H(u)$ are elements of \mathbb{R}^{nN} and \mathbb{R}^{n^2N} , respectively.

Let $a(\xi)$ be a vector of \mathbb{R}^N , continuous onto \mathbb{R}^{n^2N} , satisfying the conditions

$$(1.1) \quad a(0) = 0;$$

(C) *there exist three positive constants α , γ , and δ , with $\gamma + \delta < 1$, such that*

$$\left\| \sum_{i=1}^n \tau_{ii} - \alpha [a(\tau + \xi) - a(\xi)] \right\| \leq \gamma \|\tau\| + \delta \left\| \sum_{i=1}^n \tau_{ii} \right\|, \quad \forall \tau, \xi \in \mathbb{R}^{n^2N}.$$

These conditions are equivalent to the following ‘‘pseudo monotonicity condition’’⁽¹⁾

(C') *there exist three positive constants M , ν , and K , with $0 < \nu - K < \frac{M^2}{2\nu}$, such that, $\forall \tau, \xi \in \mathbb{R}^{n^2N}$, we have*

$$\|a(\tau + \xi) - a(\xi)\| \leq M \|\tau\|;$$

$$(a(\tau + \xi) - a(\xi)) \left| \sum_{i=1}^n \tau_{ii} \right| \geq \nu \left\| \sum_{i=1}^n \tau_{ii} \right\|^2 - K \|\tau\|^2.$$

In particular, conditions (1.1) and (C) imply

$$\|a(\tau)\| \leq \frac{c(n)}{\alpha} \|\tau\|, \quad \forall \tau \in \mathbb{R}^{n^2N}.$$

Moreover, if the matrix $\tau \in \mathbb{R}^{n^2N}$ is a solution to the system

$$a(\tau) = 0,$$

⁽¹⁾ See, for instance, [8], Section 1, and [9], Lemma 3.1.1.

then, using conditions (1.1) and (C) again, and assuming $\xi = 0$ we get

$$(1.2) \quad \left\| \sum_{i=1}^n \tau_{ii} \right\| \leq \frac{\gamma}{1-\delta} \|\tau\|,$$

where $\frac{\gamma}{1-\delta} < 1$.

More generally, if $\xi, \tau \in \mathbb{R}^{n^2N}$ are such that

$$a(\xi) = a(\tau + \xi),$$

then estimate (1.2) holds.

Define

$$H(\Omega, \mathbb{R}^N) = H^2(\Omega, \mathbb{R}^N) \cap H_0^1(\Omega, \mathbb{R}^N),$$

and pick $g \in H^2(\Omega, \mathbb{R}^N)$ ⁽²⁾.

If Ω is of class C^2 and convex, the Dirichlet problem

$$(1.3) \quad \begin{cases} u - g \in H(\Omega, \mathbb{R}^N), \\ a(H(u)) = 0 \text{ in } \Omega, \end{cases}$$

has a unique solution. In fact, setting $w = u - g$, (1.3) is equivalent to

$$(1.4) \quad \begin{cases} w \in H(\Omega, \mathbb{R}^N), \\ a(H(w) + H(g)) = 0 \text{ in } \Omega, \end{cases}$$

and, thanks to Theorem 2.1 in [7], the preceding problem has a unique solution. Moreover, it is known that the solution u to (1.3) is Hölder-continuous in Ω if $n \leq 6$ ⁽³⁾.

Then, in order to obtain the Hölder continuity of u in $\bar{\Omega}$ we clearly need to establish “boundary regularity results”. In particular, if Ω is of class C^2 and if $x^0 \in \partial\Omega$, there exists an open neighborhood \mathcal{B} of x^0 such that $\bar{\mathcal{B}}$ is mapped, by a mapping \mathcal{T} of class C^2 together with its inverse, onto the ball $\overline{B(0, 1)}$ ⁽⁴⁾, $\mathcal{T}(\Omega \cap \mathcal{B}) = B^+(1)$, and $\mathcal{T}(\partial\Omega \cap \mathcal{B}) = \Gamma$, where $\Gamma = \{x \in B(0, 1) : x_n = 0\}$. Then if u is the solution to Dirichlet problem (1.3), one has

$$(1.5) \quad \begin{cases} u \in H^2(\Omega \cap \mathcal{B}, \mathbb{R}^N), \\ u = g \quad \text{on } \partial\Omega \cap \mathcal{B}, \\ a(H(u)) = 0 \text{ in } \Omega \cap \mathcal{B}. \end{cases}$$

⁽²⁾ $H^2(\Omega, \mathbb{R}^N)$ and $H_0^1(\Omega, \mathbb{R}^N)$ are the usual Sobolev spaces.

⁽³⁾ See assertions (33) of [5], and [9], Theorem 3.2.26.

⁽⁴⁾ If σ is a positive real number, we denote by $B(0, \sigma)$ the open ball $\{x \in \mathbb{R}^n : \|x\| < \sigma\}$, and by $B^+(\sigma)$ the hemisphere $\{x \in B(0, \sigma) : x_n > 0\}$.

Making use of the transformation of co-ordinates $y = \mathcal{T}(x)$, we infer that $W(y) = U(y) - G(y) = u(\mathcal{T}^{-1}(y)) - g(\mathcal{T}^{-1}(y))$, $y \in B^+(1)$, is a solution to a problem of the type

$$(1.6) \quad \begin{cases} W \in H^2(B^+(1), \mathbb{R}^N) \\ W = 0 \quad \text{on } \Gamma \\ A(y, DW + DG, H(W) + H(G)) = 0 \quad \text{in } B^+(1). \end{cases}$$

So, it remains to establish $\mathcal{L}^{2,\lambda}$ - regularity results in $B^+(\sigma)$, with $\sigma \in (0, 1)$, for the solutions to problem (1.6). The aim of this work is to start such a study by considering at first the case in which the operator A does not depend on y and DU .

2. Differentiability near the boundary.

Let R be a positive real number. In the hemisphere $B^+(R)$, let us consider the problem

$$(2.1) \quad \begin{cases} u \in H^2(B^+(R), \mathbb{R}^N), \\ u = 0 \quad \text{on } \Gamma_R, \\ a(H(u) + H(g)) = 0 \quad \text{in } B^+(R), \end{cases}$$

where $\Gamma_R = \{x \in B(0, R) : x_n = 0\}$, $g \in H^2(B^+(R), \mathbb{R}^N)$, and $a(\xi)$ is a vector of \mathbb{R}^N , continuous onto \mathbb{R}^{n^2N} , satisfying conditions (1.1) and (C).

We want to prove the following differentiability theorem (see [3], Section 4, for the case of nonlinear elliptic systems in divergence form)

Theorem 2.1. *If $u \in H^2(B^+(R), \mathbb{R}^N)$ is a solution to problem (2.1), under conditions (1.1) and (C), and if $g \in H^3(B^+(R), \mathbb{R}^N)$, then, for every $r = 1, 2, \dots, n-1$, and $\forall \sigma, \sigma_0 \in (0, R]$, with $\sigma < \sigma_0$, one has*

$$(2.2) \quad D_r(H(u)) \in L^2(B^+(\sigma), \mathbb{R}^{n^2N}),$$

and the following estimate holds

$$(2.3) \quad \int_{B^+(\sigma)} \|D_r(H(u))\|^2 dx \leq c \left\{ \frac{1}{(\sigma_0 - \sigma)^4} \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + \frac{1}{(\sigma_0 - \sigma)^2} \int_{B^+(\sigma_0)} \|H(u)\|^2 dx + \int_{B^+(\sigma_0)} \|D_r(H(g))\|^2 dx \right\},$$

where the constant c does not depend on σ and σ_0 .

In particular, if $0 < \sigma \leq R/2$, it results

$$(2.4) \quad \int_{B^+(\sigma)} \|D_r(H(u))\|^2 dx \leq c \left\{ \frac{1}{\sigma^2} \int_{B^+(2\sigma)} \|H(u)\|^2 dx + \int_{B^+(2\sigma)} \|D_r(H(g))\|^2 dx \right\}.$$

Proof. Let $\sigma, \sigma_0 \in (0, R]$, with $\sigma < \sigma_0$, and let $\sigma_1 = \frac{\sigma + \sigma_0}{2}$. For every $x \in B^+(\sigma_1)$, $|h| < \frac{\sigma_0 - \sigma}{2}$, and $r = 1, 2, \dots, n - 1$, we put

$$\tau_{r,h}u(x) = u(x + he^r) - u(x),$$

where $\{e^r\}_{r=1,2,\dots,n}$ is the canonic basis of \mathbb{R}^n .

We proceed exactly as in the interior differentiability case (see [5]).

Let $\vartheta(x) \in C_0^\infty(\mathbb{R}^n)$ be a function fulfilling the conditions

$$0 \leq \vartheta \leq 1, \vartheta = 1 \text{ in } B(\sigma), \vartheta = 0 \text{ in } \mathbb{R}^n \setminus B(\sigma_1), |D^\alpha \vartheta| \leq c(\sigma_0 - \sigma)^{-|\alpha|},$$

$$\forall \alpha : |\alpha| \leq 2 \text{ (}^5\text{)}.$$

Set $w = u + g$. From system (2.1) we deduce that

$$\tau_{r,h}a(H(w)) = a(H(w(x + he^r))) - a(H(w(x))) = 0 \text{ in } B^+(\sigma_1)$$

and hence

$$(2.5) \quad a(H(\tau_{r,h}w) + H(w)) - a(H(w)) = 0 \text{ in } B^+(\sigma_1).$$

By (2.5) estimate (1.2) holds for the matrix $\tau = H(\tau_{r,h}w)$. Consequently,

$$(2.6) \quad \|\vartheta \Delta(\tau_{r,h}w)\| \leq \frac{\gamma}{1 - \delta} \|\vartheta H(\tau_{r,h}w)\| \text{ in } B^+(\sigma_1).$$

Since $\frac{\gamma}{1 - \delta} < 1$, we get

$$\|\vartheta \Delta(\tau_{r,h}u)\| - \|\vartheta \Delta(\tau_{r,h}g)\| \leq \|\vartheta \Delta(\tau_{r,h}u) + \vartheta \Delta(\tau_{r,h}g)\| \leq$$

⁽⁵⁾ $D^\alpha = D_1^{\alpha_1} D_2^{\alpha_2} \dots D_n^{\alpha_n}$, $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_n)$, $|\alpha| = \alpha_1 + \alpha_2 + \dots + \alpha_n$, α_i integer ≥ 0 .

$$\leq \frac{\gamma}{1-\delta} \|\vartheta H(\tau_{r,h}u)\| + \|\vartheta H(\tau_{r,h}g)\|$$

that is

$$(2.7) \quad \|\vartheta \Delta(\tau_{r,h}u)\| \leq \frac{\gamma}{1-\delta} \|\vartheta H(\tau_{r,h}u)\| + 2\|\tau_{r,h}H(g)\| \quad \text{in } B^+(\sigma_1).$$

Now, setting

$$\mathcal{U} = \vartheta \tau_{r,h}u, \quad \text{in } B^+(\sigma_1),$$

we obtain $\mathcal{U}(x) = \vartheta(x)[u(x + he^r) - u(x)] = 0$, $\forall x \in \Gamma_{\sigma_1}$ ⁽⁶⁾, because $u = 0$ on Γ_R , and

$$\mathcal{U} \in H^2(B^+(\sigma_1), \mathbb{R}^N) \cap H_0^1(B^+(\sigma_1), \mathbb{R}^N).$$

Moreover, we have

$$(2.8) \quad \Delta \mathcal{U} = \vartheta \Delta(\tau_{r,h}u) + A(u),$$

$$(2.9) \quad H(\mathcal{U}) = \vartheta H(\tau_{r,h}u) + B(u),$$

where

$$(2.10) \quad A(u) = \Delta \vartheta \cdot \tau_{r,h}u + 2 \sum_{i=1}^n D_i \vartheta D_i(\tau_{r,h}u),$$

$$(2.11) \quad B(u) = \{D_{ij} \vartheta \cdot \tau_{r,h}u + D_i \vartheta D_j(\tau_{r,h}u) + D_j \vartheta D_i(\tau_{r,h}u)\}_{i,j=1,2,\dots,n}.$$

From (2.7), (2.8), and (2.9) we obtain

$$\|\Delta \mathcal{U}\| \leq \frac{\gamma}{1-\delta} \|H(\mathcal{U})\| + \|A(u)\| + \|B(u)\| + 2\|\tau_{r,h}H(g)\| \quad \text{in } B^+(\sigma_1).$$

Hence, given any $\varepsilon > 0$, we get

$$(2.12) \quad \|\Delta \mathcal{U}\|^2 \leq (1 + \varepsilon) \left(\frac{\gamma}{1-\delta} \right)^2 \|H(\mathcal{U})\|^2 + c(\varepsilon) (\|A(u)\|^2 + \|B(u)\|^2 + \|\tau_{r,h}H(g)\|^2) \quad \text{in } B^+(\sigma_1).$$

⁽⁶⁾ $\Gamma_{\sigma_1} = \{x \in B(0, \sigma_1) : x_n = 0\}$.

Integrating on $B^+(\sigma_1)$ and using the Miranda-Talenti estimate (see, for instance, [5], Lemma 1), besides (2.12) yields

$$\int_{B^+(\sigma_1)} \|H(\mathcal{U})\|^2 dx \leq (1 + \varepsilon) \left(\frac{\gamma}{1 - \delta}\right)^2 \int_{B^+(\sigma_1)} \|H(\mathcal{U})\|^2 dx + c(\varepsilon) \int_{B^+(\sigma_1)} (\|A(u)\|^2 + \|B(u)\|^2 + \|\tau_{r,h}H(g)\|^2) dx.$$

Since $\frac{\gamma}{1-\delta} < 1$, for $\varepsilon \in (0, (\frac{1-\delta}{\gamma})^2 - 1)$ and by virtue of (2.9), we deduce

$$\int_{B^+(\sigma)} \|\tau_{r,h}H(u)\|^2 dx \leq c(\gamma, \delta) \int_{B^+(\sigma_1)} (\|A(u)\|^2 + \|B(u)\|^2 + \|\tau_{r,h}H(g)\|^2) dx.$$

From this, using a well-known lemma (see [2], Chap. I, Lemma 3.VI), it follows

$$(2.13) \quad \int_{B^+(\sigma)} \|\tau_{r,h}H(u)\|^2 dx \leq c(\gamma, \delta) \left\{ \int_{B^+(\sigma_1)} (\|A(u)\|^2 + \|B(u)\|^2) dx + |h|^2 \int_{B^+(\sigma_0)} \|D_r H(g)\|^2 dx \right\}.$$

We shall now evaluate the first integral in the right-hand side of (2.13). Using Lemma 3.VI of Chap. I in [2], we get

$$(2.14) \quad \int_{B^+(\sigma_1)} \|A(u)\|^2 dx \leq c(\sigma_0 - \sigma)^{-4} \int_{B^+(\sigma_1)} \|\tau_{r,h}u\|^2 dx + c(\sigma_0 - \sigma)^{-2} \int_{B^+(\sigma_1)} \|\tau_{r,h}Du\|^2 dx \leq c(\sigma_0 - \sigma)^{-4} |h|^2 \cdot \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + c(\sigma_0 - \sigma)^{-2} |h|^2 \int_{B^+(\sigma_0)} \|D_r(Du)\|^2 dx.$$

The integral of $\|B(u)\|^2$ is estimated in an analogous way, and we have

$$(2.15) \quad \int_{B^+(\sigma_1)} \|B(u)\|^2 dx \leq c(\sigma_0 - \sigma)^{-4} |h|^2 \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + c(\sigma_0 - \sigma)^{-2} |h|^2 \int_{B^+(\sigma_0)} \|D_r(Du)\|^2 dx.$$

Finally, (2.13), (2.14), and (2.15) lead to

$$\int_{B^+(\sigma)} \|\tau_{r,h} H(u)\|^2 dx \leq c|h|^2 \left\{ (\sigma_0 - \sigma)^{-4} \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + (\sigma_0 - \sigma)^{-2} \int_{B^+(\sigma_0)} \|D_r(Du)\|^2 dx + \int_{B^+(\sigma_0)} \|D_r(H(g))\|^2 dx \right\}.$$

So, by virtue of Nirenberg's Lemma (see, for instance, [6], Lemma 2.I), we can conclude that there exists $D_r(H(u)) \in L^2(B^+(\sigma), \mathbb{R}^{n^2 N})$, $r = 1, 2, \dots, n-1$, and

$$(2.16) \quad \int_{B^+(\sigma)} \|D_r(H(u))\|^2 dx \leq \frac{c}{(\sigma_0 - \sigma)^2} \left\{ \frac{1}{(\sigma_0 - \sigma)^2} \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + \int_{B^+(\sigma_0)} \|D_r(Du)\|^2 dx \right\} + c \int_{B^+(\sigma_0)} \|D_r(H(g))\|^2 dx.$$

Thus, (2.2) and (2.3) are proved.

Now, if $0 < \sigma \leq \frac{R}{2}$, estimate (2.16), written for $\sigma_0 = 2\sigma$, gives

$$(2.17) \quad \int_{B^+(\sigma)} \|D_r(H(u))\|^2 dx \leq c\sigma^{-2} \left\{ \sigma^{-2} \int_{B^+(2\sigma)} \|D_r u\|^2 dx + \int_{B^+(2\sigma)} \|D_r(Du)\|^2 dx \right\} + c \int_{B^+(2\sigma)} \|D_r(H(g))\|^2 dx.$$

On the other hand, from the condition $D_r u = 0$ on Γ_R , and taking into account Poincarè's inequality, one has

$$(2.18) \quad \int_{B^+(2\sigma)} \|D_r u\|^2 dx \leq c\sigma^2 \int_{B^+(2\sigma)} \|D_n(D_r u)\|^2 dx.$$

Finally, estimate (2.4) is consequence of (2.17) and (2.18). \square

In the case $r = n$ the following result holds

Theorem 2.2. *If $u \in H^2(B^+(R), \mathbb{R}^N)$ is a solution to problem (2.1), under conditions (1.1) and (C), and if $g \in H^3(B^+(R), \mathbb{R}^N)$, then, $\forall \sigma, \sigma_0 \in (0, R]$, with $0 < \sigma_0 - \sigma \leq 1$, one has*

$$(2.19) \quad D_n(D_{nn}u) \in L^2(B^+(\sigma), \mathbb{R}^N),$$

and the following estimate holds

$$(2.20) \quad \int_{B^+(\sigma)} \|D_n(D_{nn}u)\|^2 dx \leq \tilde{\gamma}^2 c \left\{ \frac{1}{(\sigma_0 - \sigma)^4} \sum_{r=1}^{n-1} \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + \right. \\ \left. + \frac{1}{(\sigma_0 - \sigma)^2} \int_{B^+(\sigma_0)} \|H(u)\|^2 dx + \int_{B^+(\sigma_0)} \|D(H(g))\|^2 dx \right\},$$

where the constant c does not depend on σ and σ_0 , while $\tilde{\gamma}$ is the constant that arises from the application of Lemma 9.3 in [1].

In particular, if $0 < \sigma \leq \min(1, \frac{R}{2})$, it results

$$(2.21) \quad \int_{B^+(\sigma)} \|D_n(D_{nn}u)\|^2 dx \leq \tilde{\gamma}^2 c \left\{ \frac{1}{\sigma^2} \int_{B^+(2\sigma)} \|H(u)\|^2 dx + \right. \\ \left. + \int_{B^+(2\sigma)} \|D(H(g))\|^2 dx \right\}.$$

Proof. Let $\sigma, \sigma_0 \in (0, R]$, with $0 < \sigma_0 - \sigma \leq 1$, let $\sigma_1 = \frac{\sigma + \sigma_0}{2}$, and let $|h| < \frac{\sigma_0 - \sigma}{2}$. Write $w = u + g$, $\tau_{n,-h} B^+(\sigma_1) = \{x \in \mathbb{R}^n : x - he^n \in B^+(\sigma_1)\}$, $\mathcal{B}^+(\sigma_1, -h) = B^+(\sigma_1) \cap \tau_{n,-h} B^+(\sigma_1)$. From system (2.1), we have

$$\tau_{n,-h} a(H(w)) = a(H(w(x - he^n))) - a(H(w(x))) = 0 \text{ in } \mathcal{B}^+(\sigma_1, -h).$$

Hence, for every $\nu = 1, 2, \dots, N$ ⁽⁷⁾

$$\tau_{n,-h} a^\nu(H(w)) = a^\nu(H(w(x - he^n))) - a^\nu(H(w(x))) = \\ = \sum_{\mu=1}^N \sum_{i,j=1}^n \left(\int_0^1 \frac{\partial a^\nu(H(w) + t\tau_{n,-h}H(w))}{\partial \xi_{ij}^\mu} dt \right) \tau_{n,-h} D_{ij} w^\mu = 0.$$

From this it follows

$$(2.22) \quad \sum_{i,j=1}^n A_{ij}(x) \tau_{n,-h} D_{ij} w = 0 \text{ in } \mathcal{B}^+(\sigma_1, -h),$$

⁽⁷⁾ Conditions (1.1) and (C) ensure that the function $\xi \rightarrow a(\xi)$ is differentiable almost everywhere in \mathbb{R}^{nN} (see, in the case $N = 1$ and $n = 2$, [10], and, for the general case, [9], Lemma 3.1.2).

where $A_{ij}(x)$ is the $N \times N$ matrix defined by

$$(2.23) \quad A_{ij}(x) = \left\{ \int_0^1 \frac{\partial a^\nu(H(w) + t\tau_{n,-h}H(w))}{\partial \xi_{ij}^\mu} dt \right\}_{\nu,\mu=1,2,\dots,N},$$

for $i, j = 1, 2, \dots, n$, and $x \in \mathcal{B}^+(\sigma_1, -h)$.

Under the hypotheses made above, there exist two constants \tilde{M} and $\tilde{\nu}$, $\tilde{M} \geq \tilde{\nu} > 0$, such that, for almost all $x \in \mathcal{B}^+(\sigma_1, -h)$, $\forall \eta \in \mathbb{R}^N$, and $\forall \lambda \in \mathbb{R}^n$, it results (see [4], [9], and [10])

$$(2.24) \quad \sum_{i,j=1}^n \|A_{ij}(x)\|^2 \leq \tilde{M}^2,$$

$$(2.25) \quad \sum_{i,j=1}^n \lambda_i \lambda_j (A_{ij}(x)\eta|\eta) \geq \tilde{\nu} \|\lambda\|^2 \|\eta\|^2.$$

In particular, by (2.25),

$$(A_{nn}(x)\eta|\eta) \geq \tilde{\nu} \|\eta\|^2,$$

for almost all $x \in \mathcal{B}^+(\sigma_1, -h)$, and $\forall \eta \in \mathbb{R}^N$, so that

$$\det A_{nn} \neq 0 \quad \text{and} \quad \|A_{nn}^{-1}(x)\| \leq \frac{\sqrt{N}}{\tilde{\nu}}, \quad \forall x \in \mathcal{B}^+(\sigma_1, -h).$$

Now, using (2.22), yields

$$(2.26) \quad \begin{aligned} \tau_{n,-h} D_{nn} u &= A_{nn}^{-1} \left[- \sum_{\substack{i,j=1 \\ i+j < 2n}}^n A_{ij}(x) \tau_{n,-h} D_{ij} u - \right. \\ &\quad \left. - \sum_{i,j=1}^n A_{ij}(x) \tau_{n,-h} D_{ij} g \right] \text{ in } \mathcal{B}^+(\sigma_1, -h). \end{aligned}$$

On the other hand, for every $\varphi \in C_0^\infty(B^+(\sigma_1), \mathbb{R}^N)$, we have

$$\begin{aligned} \int_{B^+(\sigma_1)} (D_{nn} u | \tau_{n,h} \varphi) dx &= \int_{\tau_{n,-h} B^+(\sigma_1)} (D_{nn} u(x - h e^n) | \varphi(x)) dx - \\ &\quad - \int_{B^+(\sigma_1)} (D_{nn} u(x) | \varphi(x)) dx = \end{aligned}$$

$$\begin{aligned} &= \int_{\mathcal{B}^+(\sigma_1, -h)} (D_{nn}u(x - he^n)|\varphi(x)) dx - \int_{B^+(\sigma_1)} (D_{nn}u(x)|\varphi(x)) dx = \\ &= \int_{\mathcal{B}^+(\sigma_1, -h)} (\tau_{n, -h} D_{nn}u|\varphi) dx - \int_{B^+(\sigma_1) \setminus \mathcal{B}^+(\sigma_1, -h)} (D_{nn}u|\varphi) dx. \end{aligned}$$

If $|h|$ is small enough, the last integral vanishes because φ has a compact support in $B^+(\sigma_1)$. Then, taking into account (2.26) and (2.24), if $|h|$ is small enough we get ⁽⁸⁾

$$\begin{aligned} (2.27) \quad & \left| \int_{B^+(\sigma_1)} (D_{nn}u|\tau_{n, h}\varphi) dx \right| = \left| \int_{\mathcal{B}^+(\sigma_1, -h)} \left(- \sum_{\substack{i, j=1 \\ i+j < 2n}}^n A_{ij}(x)\tau_{n, -h}D_{ij}u - \right. \right. \\ & \left. \left. - \sum_{i, j=1}^n A_{ij}(x)\tau_{n, -h}D_{ij}g|(A_{nn}^{-1})^*\varphi) dx \right| \leq c(\tilde{\nu}, \tilde{M}) \left(\int_{B^+(\sigma_1)} \|\varphi(x)\|^2 dx \right)^{\frac{1}{2}}. \\ & \left\{ \sum_{\substack{i, j=1 \\ i+j < 2n}}^n \int_{\mathcal{B}^+(\sigma_1, -h)} \|\tau_{n, -h}D_{ij}u\|^2 dx + \sum_{i, j=1}^n \int_{\mathcal{B}^+(\sigma_1, -h)} \|\tau_{n, -h}D_{ij}g\|^2 dx \right\}^{\frac{1}{2}} \leq \\ & \leq c(\tilde{\nu}, \tilde{M})|h| \left(\int_{B^+(\sigma_1)} \|\varphi(x)\|^2 dx \right)^{\frac{1}{2}}. \\ & \left\{ \sum_{\substack{i, j=1 \\ i+j < 2n}}^n \int_{B^+(\sigma_1)} \|D_n(D_{ij}u)\|^2 dx + \sum_{i, j=1}^n \int_{B^+(\sigma_1)} \|D_n(D_{ij}g)\|^2 dx \right\}^{\frac{1}{2}}. \end{aligned}$$

On the other hand, by (2.3), it follows, for every $i, j = 1, 2, \dots, n$, with $i + j < 2n$

$$\begin{aligned} (2.28) \quad & \int_{B^+(\sigma_1)} \|D_n(D_{ij}u)\|^2 dx \leq c \left\{ \frac{1}{(\sigma_0 - \sigma)^4} \sum_{r=1}^{n-1} \int_{B^+(\sigma_0)} \|D_r u\|^2 dx + \right. \\ & \left. + \frac{1}{(\sigma_0 - \sigma)^2} \int_{B^+(\sigma_0)} \|H(u)\|^2 dx + \int_{B^+(\sigma_0)} \|D(H(g))\|^2 dx \right\} = c\mathcal{M}^2, \end{aligned}$$

where the constant c does not depend on σ and σ_0 .

From (2.27) and (2.28), we deduce

$$\left| \int_{B^+(\sigma_1)} (D_{nn}u|\tau_{n, h}\varphi) dx \right| \leq c \mathcal{M} |h| \left(\int_{B^+(\sigma_1)} \|\varphi(x)\|^2 dx \right)^{\frac{1}{2}},$$

⁽⁸⁾ $(A_{nn}^{-1})^*$ is the adjoint of the matrix A_{nn}^{-1} .

while, dividing both sides by $|h|$ and letting $h \rightarrow 0$, we obtain, for every $\varphi \in C_0^\infty(B^+(\sigma_1), \mathbb{R}^N)$

$$(2.29) \quad \left| \int_{B^+(\sigma_1)} (D_{nn}u | D_n \varphi) dx \right| \leq c \mathcal{M} \left(\int_{B^+(\sigma_1)} \|\varphi(x)\|^2 dx \right)^{\frac{1}{2}}.$$

Now, through (2.29) and Lemma 9.3 in [1] (see also [3], Lemma 2.III), we achieve condition (2.19) and the following inequality

$$(2.30) \quad \int_{B^+(\sigma)} \|D_n(D_{nn}u)\|^2 dx \leq \tilde{\gamma}^2 c \left\{ \mathcal{M}^2 + \sum_{i=1}^{n-1} \int_{B^+(\sigma_1)} \|D_i(D_{nn}u)\|^2 dx + \int_{B^+(\sigma_1)} \|D_{nn}u\|^2 dx \right\},$$

where the constant c does not depend on σ and σ_0 , while $\tilde{\gamma}$ is the constant that arises from the application of Lemma 9.3 in [1].

From this, thanks to estimate (2.28) and the hypothesis $\sigma_0 - \sigma \leq 1$, inequality (2.20) follows.

Now, if $0 < \sigma \leq \min(1, \frac{R}{2})$, estimate (2.20), written for $\sigma_0 = 2\sigma$, gives

$$(2.31) \quad \int_{B^+(\sigma)} \|D_n(D_{nn}u)\|^2 dx \leq \tilde{\gamma}^2 c \left\{ \sigma^{-4} \sum_{r=1}^{n-1} \int_{B^+(2\sigma)} \|D_r u\|^2 dx + \sigma^{-2} \int_{B^+(2\sigma)} \|H(u)\|^2 dx + \int_{B^+(2\sigma)} \|D(H(g))\|^2 dx \right\}.$$

On the other hand, from the condition $D_r u = 0$ on Γ_R , $r = 1, 2, \dots, n-1$, and taking into account Poincarè's inequality one has

$$(2.32) \quad \int_{B^+(2\sigma)} \|D_r u\|^2 dx \leq c \sigma^2 \int_{B^+(2\sigma)} \|D_n(D_r u)\|^2 dx, \quad r = 1, 2, \dots, n-1.$$

By (2.31) and (2.32), we obtain

$$\int_{B^+(\sigma)} \|D_n(D_{nn}u)\|^2 dx \leq \tilde{\gamma}^2 c \left\{ \sigma^{-2} \sum_{r=1}^{n-1} \int_{B^+(2\sigma)} \|D_n(D_r u)\|^2 dx + \sigma^{-2} \int_{B^+(2\sigma)} \|H(u)\|^2 dx + \int_{B^+(2\sigma)} \|D(H(g))\|^2 dx \right\},$$

which leads to (2.21). \square

Obviously, using Theorems 2.1 and 2.2 we can state the following differentiability result

Theorem 2.3. *If $u \in H^2(B^+(R), \mathbb{R}^N)$ is a solution to problem (2.1), under conditions (1.1) and (C), and if $g \in H^3(B^+(R), \mathbb{R}^N)$, then, for every $\sigma \in (0, R)$, one has*

$$H(u) \in H^1(B^+(\sigma), \mathbb{R}^{n^2N}).$$

3. Results on Hölder continuity.

$\mathcal{L}^{2,\lambda}$ - regularity and hence Hölder continuity results concerning the vectors Du and u can be derived from Theorem 2.3. In fact, we have the following

Theorem 3.1. *If $u \in H^2(B^+(R), \mathbb{R}^N)$ is a solution to problem (2.1), under conditions (1.1) and (C), and if $g \in H^3(B^+(R), \mathbb{R}^N)$, then, for every $\sigma \in (0, R)$, $\forall q > 2$, and $\forall \lambda \in (n, n + 2)$, one has*

$$(3.1) \quad H(u) \in \mathcal{L}^{2,2-\frac{4}{q}}(B^+(\sigma), \mathbb{R}^{n^2N}), \quad Du \in \mathcal{L}^{2,4-\frac{4}{q}}(B^+(\sigma), \mathbb{R}^{nN}),$$

$$(3.2) \quad u \in \mathcal{L}^{2,6-\frac{4}{q}}(B^+(\sigma), \mathbb{R}^N), \quad \text{if } n \geq 4,$$

$$(3.3) \quad u \in \mathcal{L}^{2,\lambda}(B^+(\sigma), \mathbb{R}^N), \quad \text{if } n = 2 \text{ or } n = 3.$$

Proof. Fixing $\sigma \in (0, R)$, by virtue of Theorem 2.3, we get

$$H(u) \in H^1(B^+(\sigma), \mathbb{R}^{n^2N}).$$

Thus, if $n > 2$, the Sobolev imbedding Theorem, provides

$$(3.4) \quad H(u) \in L^{2^*}(B^+(\sigma), \mathbb{R}^{n^2N}),$$

where $\frac{1}{2^*} = \frac{1}{2} - \frac{1}{n}$.

Now, $\forall x^0 \in \overline{B^+(\sigma)}$ and $\forall \rho \in (0, R - \sigma)$, set $B_\sigma^+(x^0, \rho) = B^+(\sigma) \cap B(x^0, \rho)$ ⁽⁹⁾. Thanks to condition (3.4) and Hölder's inequality, one has

$$(3.5) \quad \int_{B_\sigma^+(x^0, \rho)} \|H(u)\|^2 dx \leq c\rho^2 \left(\int_{B^+(\sigma)} \|H(u)\|^{2^*} dx \right)^{\frac{2}{2^*}}.$$

⁽⁹⁾ $B(x^0, \rho) = \{x \in \mathbb{R}^n : \|x - x^0\| < \rho\}$.

If $n = 2$, by the Sobolev imbedding Theorem again, it follows

$$H(u) \in L^q(B^+(\sigma), \mathbb{R}^{nN}), \quad \forall q > 2;$$

therefore, $\forall x^0 \in \overline{B^+(\sigma)}$, $\forall \rho \in (0, R - \sigma)$, and $\forall q > 2$, we get

$$(3.6) \quad \int_{B_\sigma^+(x^0, \rho)} \|H(u)\|^2 dx \leq c\rho^{2-\frac{4}{q}} \left(\int_{B^+(\sigma)} \|H(u)\|^q dx \right)^{\frac{2}{q}}.$$

Clearly, if $n \geq 2$, by (3.5) and (3.6), one has

$$(3.7) \quad \int_{B_\sigma^+(x^0, \rho)} \|H(u)\|^2 dx \leq c\rho^{2-\frac{4}{q}} M_{\sigma, q},$$

$\forall x^0 \in \overline{B^+(\sigma)}$, $\forall \rho \in (0, \min(1, R - \sigma))$, and $\forall q > 2$, where

$$M_{\sigma, q} = \begin{cases} \left(\int_{B^+(\sigma)} \|H(u)\|^{2^*} dx \right)^{\frac{2}{2^*}}, & \text{if } n > 2, \\ \left(\int_{B^+(\sigma)} \|H(u)\|^q dx \right)^{\frac{2}{q}}, & \text{if } n = 2. \end{cases}$$

Hence, the first assertion in (3.1) is true.

Finally, conditions

$$(3.8) \quad Du \in \mathcal{L}^{2, 4-\frac{4}{q}}(B^+(\sigma), \mathbb{R}^{nN}), \quad \forall q > 2,$$

(3.2), and (3.3) follow from the first assertion in (3.1) and Poincaré's inequality (see [2], Chap. I, Theorem 3.IV). \square

Results on the Hölder continuity of the solutions to problem (2.1) and their gradient in $\overline{B^+(\sigma)}$, $0 < \sigma < R$, can be immediately obtained from Theorem 3.1.

In fact, if $2 \leq n < 4$, then there exists $q > 2$ such that $4 - \frac{4}{q} > n$, and hence, by (3.8) and well-known properties of isomorphism between the spaces $\mathcal{L}^{2, \lambda}$ and $C^{0, \alpha}$, one has

$$Du \text{ is Hölder-continuous in } \overline{B^+(\sigma)}.$$

If $4 \leq n < 6$, then there exists $q > 2$ such that $6 - \frac{4}{q} > n$, and hence, by (3.2), it follows

$$u \text{ is Hölder-continuous in } \overline{B^+(\sigma)}.$$

Finally, if $2 \leq n \leq 3$, (3.3) holds, and this ensures that $u \in C^{0, \alpha}(\overline{B^+(\sigma)}, \mathbb{R}^N)$, $\forall \alpha \in (0, 1)$.

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